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## 第二章 位势方程

$$\Delta u = f \quad \text{in } \Omega \quad \begin{cases} f=0 & \text{Laplace} \\ f \neq 0 & \text{Poisson} \end{cases}$$

$u$  仅为  $x$  函数

Dirichlet  $u|_{\partial\Omega} = \varphi$

Neumann  $\frac{\partial u}{\partial n}|_{\partial\Omega} = \varphi$

Robin  $\frac{\partial u}{\partial n} + \sigma u|_{\partial\Omega} = \varphi$

**Rmk** 波方程  $\partial_t^2 u - \Delta u = f$ ,  $u$  若不随  $t$  变化, 则此为位势方程

位势方程可视为波动方程稳态解

### § 2.1 调和函数

#### def 1. 调和函数

$u: \Omega \rightarrow \mathbb{R}$ , 有 2 阶连续偏导数,  $\Delta u = 0$

def.  $u$  为调和函数

#### Recall. 公式

1.  $f: \mathbb{R}^n \rightarrow \mathbb{R}$

$$\int_{\mathbb{R}^n} f(x) dx = \int_0^\infty \int_{\partial B(x_0, r)} f(y) dS(y) dr$$

$$(y = x_0 + rw) = \int_0^\infty \int_{|w|=1} f(x_0 + rw) dS(w) r^{n-1} dr$$

$$\int_{B_{r_0}(x_0)} f(x) dx = \int_0^{r_0} \int_{|w|=1} f(x_0 + rw) dS(w) r^{n-1} dr$$

$$2. \frac{d}{dr} \int_{B(x_0, r)} f(y) dy = \int_{\partial B(x_0, r)} f(y) dS(y)$$

#### def 2. 平均值性质

$u \in C(\Omega)$ ,  $u$  满足平均值:

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$$\forall B_r(x) \subset \Omega, \text{ 有 } u(x) = \frac{1}{|B_r(x)|} \int_{B_r(x)} u(y) dy \quad \textcircled{1}$$

$$\Omega \in \mathbb{R}^3, |B_r(x)| = \frac{4}{3}\pi r^3$$

$u$  满足第二平均值:

$$\forall B_r(x) \subset \Omega, \text{ 有 } u(x) = \frac{1}{|\partial B_r(x)|} \int_{\partial B_r(x)} u(y) dS(y) \quad \textcircled{2}$$

$$\Omega \in \mathbb{R}^3, |\partial B_r(x)| = 4\pi r^2, u(x) = \frac{1}{4\pi} \int_{|w|=1} u(x+rw) dw$$

claim:  $\textcircled{1} \Leftrightarrow \textcircled{2}$

$\textcircled{2} \Rightarrow \textcircled{1}$ :

$$\begin{aligned} \forall B_r(x) \subseteq \Omega, \int_{B_r(x)} u(y) dy &= \int_0^r \left( \int_{\partial B(x,\rho)} u(y) dS(y) \right) d\rho \\ &\stackrel{\textcircled{2}}{=} \int_0^r |\partial B(x,\rho)| u(x) d\rho \\ &= u(x) \int_0^r |\partial B(x,\rho)| d\rho = u(x) |B(x,r)| \Rightarrow \textcircled{1} \end{aligned}$$

$\textcircled{1} \Rightarrow \textcircled{2}$ :

$$\text{(注意到: } |B(x,r)| = \int_0^r |\partial B(x,\rho)| d\rho \text{)}$$

$$\forall B_r(x) \subseteq \Omega, |B_r(x)| u(x) = \int_{B_r(x)} u(y) dy$$

$$\text{对 } r \text{ 微分, 有 } |\partial B(x,r)| u(x) = \int_{\partial B(x,r)} u(y) dS(y) \Leftrightarrow \textcircled{2}$$

### thm 1. 调和函数 $\Rightarrow$ 平均值

$u \in C^2(\Omega)$ , 为  $\Omega$  上调和函数, 对任意  $B_r(x) \subseteq \Omega$ ,

$$u(x) = \frac{1}{|\partial B_r(x)|} \int_{\partial B_r(x)} u(y) dS(y)$$

pr:  $\Delta u = 0$ , in  $\Omega \quad \forall B_r(x) \subset \Omega$

$$0 = \int_{B_r(x)} \Delta u dy = \int_{B_r(x)} \operatorname{div}(\nabla u) dy = \int_{\partial B_r(x)} \nabla u \cdot \bar{n} dS(y)$$

$$= \int_{|y-x|=r} \nabla u(y) \cdot \frac{y-x}{r} dS(y)$$

$$= \int_{|w|=1} \omega \cdot \nabla u(x+rw) r^{n-1} dw \quad (\omega \text{ 为 } r \text{ 半径球面上的积元})$$

$$= r^{n-1} \int_{|w|=1} \frac{d}{dr} (u(x+rw)) dw$$

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$$= r^{n-1} \frac{d}{dr} \int_{|w|=1} u(x+rw) dw$$

$$\Rightarrow \forall r, \int_{|w|=1} u(x+rw) dw = \int_{|w|=1} u(x) dw = |\partial B(x,r)| u(x)$$

$$\text{故 } u(x) = \frac{1}{|\partial B(x,r)|} \int_{|w|=1} u(x+rw) dw$$

$$\begin{aligned} & \stackrel{y=x+rw}{=} \frac{1}{|\partial B(x,r)|} \int_{\partial B(x,r)} u(y) dS(y) \end{aligned}$$

## Thm 2. 平均值 $\Rightarrow$ 调和. 光滑

$u \in C(\Omega)$ , 满足  $\forall B(x,r) \subset \Omega$ .

$$u(x) = \frac{1}{|\partial B(x,r)|} \int_{\partial B(x,r)} u(y) dS(y)$$

则  $u$  光滑且为调和函数

## Recall 卷积

$$(f+g)(x) \stackrel{\text{def.}}{=} \int f(x-y)g(y) dy$$

$f, g$  中若一者光滑, 则  $(f+g)(x)$  光滑

pr. 令  $\varphi \in C_0^\infty(B_1(0))$  (在一个邻域外恒为 0)

$$\int_{\mathbb{R}^n} \varphi(x) dx = 1 = \int_{B_1(0)} \varphi(x) dx$$

$\varphi(x) = \varphi(|x|)$  (令  $\varphi$  球面对称, 仅为  $r$  函数, 与角度无关)

$$\text{则 } \int_0^1 \int_{|w|=1} \varphi(r) r^{n-1} dw dr$$

$$= \omega_n \int_0^1 \varphi(r) r^{n-1} dr \quad (\omega_n \text{ 表示 } n \text{ 维单位球面面积})$$

$$= 1 \quad (\text{利用了径向对称})$$

$$\text{def: } \varphi_\varepsilon(x) = \frac{1}{\varepsilon^n} \varphi\left(\frac{x}{\varepsilon}\right)$$

$$\varphi_\varepsilon \in C_0^\infty(B_\varepsilon(0))$$

$$\int_{\mathbb{R}^n} \varphi_\varepsilon(x) dx = \int_{\mathbb{R}^n} \frac{1}{\varepsilon^n} \varphi\left(\frac{x}{\varepsilon}\right) dx \stackrel{x=\varepsilon y}{=} \int_{\mathbb{R}^n} \varphi(y) dy = 1$$

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claim:

$\forall x \in \Omega$ , 取  $\varepsilon = \frac{1}{4} \text{dist}(x, \partial\Omega)$ , 则

$$u(x) = (u * \varphi_\varepsilon)(x)$$

$$(u * \varphi_\varepsilon)(x) = \int_{\Omega} u(y) \varphi_\varepsilon(x-y) dy$$

$$= \int_{\Omega \cap B_\varepsilon(x)} u(y) \frac{1}{\varepsilon^n} \varphi\left(\frac{x-y}{\varepsilon}\right) dy$$

$$= \int_{B_\varepsilon(x)} u(y) \frac{1}{\varepsilon^n} \varphi\left(\frac{x-y}{\varepsilon}\right) dy$$

$$\stackrel{y=x+r\omega}{=} \int_0^\varepsilon \int_{|\omega|=1} u(x+r\omega) \frac{1}{\varepsilon^n} \varphi\left(\frac{r}{\varepsilon}\right) r^{n-1} dr d\omega$$

$$\stackrel{\rho=r/\varepsilon}{=} \int_0^1 \int_{|\omega|=1} u(x+\rho\omega) d\omega \rho^{n-1} \varphi(\rho) d\rho$$

$$\int_{|\omega|=1} u(x+\rho\omega) d\omega = \int_{|\omega|=1} u(x) d\omega = \omega_n u(x)$$

$$\text{故 } (u * \varphi_\varepsilon)(x) = \omega_n \int_0^1 \rho^{n-1} \varphi(\rho) d\rho u(x) = u(x)$$

$\varphi_\varepsilon$  光滑, 由卷积性质  $u$  光滑

下证明  $u$  调和

step 1  $u \in C^2(\Omega)$

step 2  $\Delta u = 0$

claim:  $\forall x, r > 0$ ,  $\int_{B_r(x)} \Delta u(y) dy = 0$

则  $\Delta u \equiv 0$

否则,  $\exists x_0$  st.  $(\Delta u)(x_0) \neq 0$ , 不妨  $= C > 0$

则  $\exists r_0 > 0$ ,  $(\Delta u)(x) > \frac{C}{2} \quad \forall x \in B_{r_0}(x_0)$

则  $\int_{B_{r_0}(x_0)} \Delta u(y) dy \geq \frac{C}{2} |B_{r_0}(x_0)| > 0$

事实上,  $\int_{B_r(x)} \Delta u(y) dy = \int_{B_r(x)} \text{div}(\nabla u)(y) dy = \int_{\partial B_r(x)} \nabla u \cdot \frac{y-x}{r} dS(y)$

$$= \int_{|\omega|=1} \omega \cdot \nabla u(x+r\omega) r^{n-1} d\omega = r^{n-1} \frac{d}{dr} \int_{|\omega|=1} u(x+r\omega) d\omega = 0$$

Hint.  $\int_{|\omega|=1} u(x+r\omega) d\omega$  与  $r$  无关  $\Leftrightarrow$  平均值性质  $\uparrow$  平均值性质

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Rmk. 平均值性质即函数值 = 邻域内/球面上函数值的平均

满足平均值性质反需可微

满足调和需要二阶连续可微

调和函数必然光滑

thm 3. (Harnack 不等式)

设  $u$  为  $\Omega$  上非负连续函数,  $u$  调和, 对  $\Omega$  上任意联通紧集  $V$ ,

$$\exists C = C(\text{dist}(V, \partial\Omega), n), \text{ s.t. } \text{dist}(V, \partial\Omega) = \inf_{\substack{x \in V \\ y \in \partial\Omega}} |x - y|$$

$$\sup_V u \leq C \inf_V u$$

Rmk.  $C$  与  $V, n$  有关, 与函数  $u$  无关

pr: claim:  $u(y) \leq C u(x)$

$$\text{令 } r = \frac{1}{4} \text{dist}(V, \partial\Omega)$$

①  $\forall x, y, |x - y| < r$ , 则  $B(x, 2r) \supset B(y, r)$

$$(\forall z \in B(y, r), |y - z| < r)$$

$$|z - x| \leq |z - y| + |y - x| < 2r, z \in B(x, 2r)$$

$u$  调和, 则  $u$  满足平均值性质

$$u(x) = \frac{1}{|B_{2r}(x)|} \int_{B_{2r}(x)} u(z) dz$$

$$\geq \frac{1}{2^n} \frac{1}{|B_r(y)|} \int_{B_r(y)} u(z) dz$$

$$= \frac{1}{2^n} u(y) \Leftrightarrow u(y) \leq 2^n u(x)$$

②  $\forall x, y \in V$

$\exists B_1, \dots, B_N, B_i \cap B_{i+1} \neq \emptyset$ , 半径为  $\frac{r}{2}$ ,  $x \in B_1, y \in B_N$

$\forall x_1, x_2 \in B_i$ , 有  $|x_1 - x_2| < r$ , 由 ①,  $u(y) \leq 2^{nN} u(x)$

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$N$  仅与  $V$  有关

$$\text{由 } x, y \text{ 的任意性, } \sup_{x \in V} u \leq 2^{NN} \inf_{x \in V} u$$

Rmk. 有限覆盖来源于  $\bigcup_{x \in V} B_r(x)$

thm 4. (梯度估计)

$u \in C(\overline{B_R(x_0)})$  是调和的, 则

$$|\nabla u(x_0)| \leq \frac{n}{R} \max_{\overline{B_R(x_0)}} |u| \quad (\text{常量为最大分量})$$

pr: 设  $u \in C^1(\overline{B_R(x_0)})$

( $u$  调和  $\Rightarrow u \in C^\infty(B_R(x_0))$  但未知边界光滑性)

$u$  调和, 则  $u$  在  $B_r$  上光滑 ( $\overline{B_R(x_0)} = \overline{B_R}$ )

故  $\partial_{x_i} u$  也调和

$$\begin{aligned} \text{由平均值性质} \quad \partial_{x_i} u(x_0) &= \frac{1}{|B_R(x_0)|} \int_{B_R(x_0)} \partial_{x_i} u(y) dy \\ &= \frac{1}{|B_R(x_0)|} \int_{\partial B_R(x_0)} u n_i dS(y) \end{aligned}$$

$$\begin{aligned} \Rightarrow |\partial_{x_i} u(x_0)| &\leq \frac{1}{|B_R(x_0)|} \int_{\partial B_R(x_0)} |u(y)| dS(y) \\ &\leq \max_{\overline{B_R}} |u| \cdot \frac{n}{R} \end{aligned}$$

thm 5.

若  $u \in C(\overline{B_R})$  为非负调和函数, 则

$$|\nabla u(x_0)| \leq \frac{n}{R} u(x_0)$$

$$\text{pr: } |\nabla u(x_0)| \leq \frac{1}{|B_R(x_0)|} \int_{\partial B_R(x_0)} u(y) dS(y) = \frac{|d\sigma_R(x_0)|}{|B_R(x_0)|} u(x_0) = \frac{n}{R} u(x_0)$$

↑  
平均值性质

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### Cor. (Liouville)

$\mathbb{R}^n$  上的上有界/下有界调和函数为常数

pr:  $u \leq M \Rightarrow u = \text{const}$

令  $v = M - u$ , 则  $v$  调和,  $v \geq 0$

$$\forall x_0, R > 0, \text{ 对 } v, |\nabla v(x_0)| \leq \frac{n}{R} v(x_0) = \frac{n}{R} (M - u(x_0))$$

令  $R \rightarrow \infty$ ,  $|\nabla v(x_0)| = 0$ . 则  $\nabla v \equiv 0$ , 即  $v$  为常数

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## §2.2 基本解和 Green 函数

### def 1 基本解

若  $\Delta u = \delta$ , 称  $u$  为基本解

$\delta$  类似于单位向量,  $\delta$  为算子,  $\langle \delta, f \rangle = f(0)$

特别地,  $\Delta u = 0, \forall x \neq 0$

### 想观察方程特殊的解的形成

( $\mathbb{R}^n$  同对称  $u(x) = u(|x|)$ )

$$\Delta u = \partial^2 u + \frac{n-1}{r} \partial_r u + \frac{1}{r^2} \Delta_\perp u = \partial^2 u + \frac{n-1}{r} \partial_r u$$

$$\text{令 } v = \partial_r u, \text{ 则 } \partial_r v + \frac{n-1}{r} v = 0$$

$$\Rightarrow v = C_1 r^{-(n-1)}$$

$$\Rightarrow u(r) = \begin{cases} C_1 r^{-(n-2)} + C_2 & n \geq 3 \\ C_1 \ln r + C_2 & n = 2 \end{cases}$$

### def 2 基本解

$$\exists x \in \mathbb{R}^n, x \neq 0, \Gamma(x) = \begin{cases} \frac{1}{2\pi} \ln|x| & n=2 \\ \frac{1}{n-2} \frac{1}{|x|^{n-2}} & n \geq 3 \end{cases}$$

且,  $\Delta \Gamma = \delta \neq 0$

### thm 1. (Green)

$u \in C^2(\Omega) \cap C^1(\bar{\Omega})$ , 则

$$\begin{aligned} \int_\Omega u \Delta v \, dx &= \int_\Omega \nabla \cdot (u \nabla v) - \nabla u \cdot \nabla v \, dx = \int_{\partial \Omega} u \nabla v \cdot \bar{n} \, ds - \int_\Omega \nabla u \cdot \nabla v \, dx \\ &= \int_{\partial \Omega} u \frac{\partial v}{\partial n} \, ds - \int_\Omega \nabla u \cdot \nabla v \, dx \quad (\text{第一 Green}) \end{aligned}$$

$$\int_\Omega u \Delta v - v \Delta u \, dx = \int_{\partial \Omega} u \frac{\partial v}{\partial n} - v \frac{\partial u}{\partial n} \, ds \quad (\text{第二 Green})$$

进一步观察方程特殊的解的表达形式

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### thm 2. 三维下 $\Delta u = 0$ in $\Omega$ 的解

$$u \in C^1(\Omega) \cap C(\bar{\Omega}), \Delta u = 0 \text{ in } \Omega$$

$$\forall x_0 \in \Omega, \text{ 有 } u(x_0) = \frac{1}{4\pi} \int_{\partial\Omega} \left[ -u \frac{\partial}{\partial n} \left( \frac{1}{|x-x_0|} \right) + \frac{1}{|x-x_0|} \frac{\partial u}{\partial n} \right] dS(x) \quad (**)$$

pr: 尝试利用 Green 公式, 但  $\frac{1}{|x-x_0|}$  具有奇性

在  $\Omega_\varepsilon = \Omega \setminus \bar{B}_\varepsilon(x_0)$  用第二 Green 公式

事实上 Laplace 方程满足平移不变性, 则不妨设  $x_0 = 0$

$$\text{点源记: 若 } 0 \in \Omega, u(0) = \frac{1}{4\pi} \int_{\partial\Omega} \left[ -u \frac{\partial}{\partial n} \left( \frac{1}{|x|} \right) + \frac{1}{|x|} \frac{\partial u}{\partial n} \right] dS(x) \quad (***)$$

若 (\*\*)(\*) 成立, 对  $u(x+x_0)$  应用 (\*\*\*)

$$\begin{aligned} u(x_0) &= \frac{1}{4\pi} \int_{\partial(\Omega-x_0)} \left[ -u(x+x_0) \frac{\partial}{\partial n} \left( \frac{1}{|x|} \right) + \frac{1}{|x|} \frac{\partial u}{\partial n} (x+x_0) \right] dS \\ &= \frac{1}{4\pi} \int_{\partial\Omega} \left[ -u(x) \frac{\partial}{\partial n} \left( \frac{1}{|x-x_0|} \right) + \frac{1}{|x-x_0|} \frac{\partial u}{\partial n} \right] dS \end{aligned}$$

在  $\Omega_2 = \Omega \setminus \bar{B}_\varepsilon(0)$  上应用第二 Green, 对  $u, v = \frac{1}{4\pi|x|}$

$$\int_{\Omega_2} (u \Delta v - v \Delta u) dx = 0$$

$$= \int_{\partial\Omega_2} u \frac{\partial v}{\partial n} - v \frac{\partial u}{\partial n} dS$$

$$= \frac{1}{4\pi} \int_{\partial\Omega} u \frac{\partial}{\partial n} \left( \frac{1}{|x|} \right) - \frac{1}{|x|} \frac{\partial u}{\partial n} dS - \frac{1}{4\pi} \int_{\partial B_\varepsilon} u \frac{\partial}{\partial n} \left( \frac{1}{|x|} \right) - \frac{1}{|x|} \frac{\partial u}{\partial n} dS \stackrel{I}{=} 1$$

$$I = \frac{1}{4\pi} \int_{|x|=\varepsilon} u \cdot \frac{1}{\varepsilon^2} dS - \frac{1}{4\pi} \int_{|x|=\varepsilon} \frac{1}{|x|} \frac{\partial u}{\partial n} dS$$

$$= \frac{1}{4\pi\varepsilon^2} \int_{|x|=\varepsilon} u(x) dS - \frac{1}{4\pi\varepsilon} \int_{B(0,\varepsilon)} \Delta u dx$$

$$\text{令 } \varepsilon \rightarrow 0, I = -u(0)$$

Rmk. 也可利用估计

$$\frac{1}{4\pi\varepsilon^2} \int_{|x|=\varepsilon} u(x) - u(0) dS \leq \frac{1}{4\pi\varepsilon^2} \int_{|x|=\varepsilon} |(Du)(\xi)| |x| dS \leq \max_{\xi \in \bar{\Omega}} |(Du)(\xi)| \cdot \frac{\varepsilon}{4\pi\varepsilon^2} \cdot 4\pi\varepsilon^2 \rightarrow 0$$

$$\frac{1}{4\pi} \int_{|x|=\varepsilon} \frac{1}{|x|} \frac{\partial u}{\partial n} dS \leq \max_{x \in \Omega} \left| \frac{\partial u}{\partial n} \right| \cdot \frac{1}{4\pi\varepsilon} \cdot 4\pi\varepsilon^2 \rightarrow 0$$

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需要  $u$  在边界的值, 但通常不给定

若  $g$  在  $\Omega$  内调和,  $g|_{\partial\Omega} = \frac{1}{4\pi|x-x_0|}$ , 则对  $u, g$  在  $\Omega$  上用第二 Green

$$0 = \int_{\partial\Omega} (u \frac{\partial g}{\partial n} - g \frac{\partial u}{\partial n}) ds$$

$$\Rightarrow u(x_0) = \int_{\partial\Omega} [u \frac{\partial}{\partial n} (g - \frac{1}{4\pi|x-x_0|}) - (g - \frac{1}{4\pi|x-x_0|}) \frac{\partial u}{\partial n}] ds$$
$$= \int_{\partial\Omega} u \frac{\partial}{\partial n} (g - \frac{1}{4\pi|x-x_0|}) ds$$

$$\text{令 } \tilde{g}(x, x_0) = -g(x) + \frac{1}{4\pi|x-x_0|}$$

$$\text{则 } u(x_0) = - \int_{\partial\Omega} u(x) \frac{\partial \tilde{g}}{\partial n}(x, x_0) dS(x) \quad \text{Poisson 公式 (2.1)}$$

$g$  的表达式应同样被给出

def 3. Green 函数

$\Omega$  上的单值  $-\Delta$  的 Green 函数, 满足

1)  $\tilde{g}(x)$  在  $\Omega$  内除  $x_0$  点外二阶连续可微且调和

2)  $\tilde{g}(x) = 0, \forall x \in \partial\Omega$

3)  $-\tilde{g}(x) + \frac{1}{4\pi|x-x_0|}$  在  $x_0$  有限, 此处二阶连续可微且调和

thm 3.1 性质:  $\tilde{g}(x, x_0) = \tilde{g}(x_0, x)$

对  $u = \tilde{g}(x, a), v = \tilde{g}(x, b)$  在  $\Omega_\varepsilon = \Omega \setminus (\overline{B_\varepsilon(a)} \cup \overline{B_\varepsilon(b)})$  应用第二 Green

$$\text{则 } 0 = \int_{\partial\Omega_\varepsilon} (u \frac{\partial v}{\partial n} - v \frac{\partial u}{\partial n}) ds$$

$$= \int_{\partial\Omega} (u \frac{\partial v}{\partial n} - v \frac{\partial u}{\partial n}) ds + \int_{|x-a|=\varepsilon} (u \frac{\partial v}{\partial n} - v \frac{\partial u}{\partial n}) ds + \int_{|x-b|=\varepsilon} (u \frac{\partial v}{\partial n} - v \frac{\partial u}{\partial n}) ds$$

$$A_\varepsilon = \int_{|x-a|=\varepsilon} [(u - \frac{1}{4\pi|x-a|}) \frac{\partial v}{\partial n} - v \frac{\partial}{\partial n} (u - \frac{1}{4\pi|x-a|})] ds + \int_{|x-a|=\varepsilon} \frac{1}{4\pi|x-a|} \frac{\partial v}{\partial n} ds - \int_{|x-a|=\varepsilon} v \frac{\partial}{\partial n} (\frac{1}{4\pi|x-a|}) ds$$

$$\textcircled{1} = - \int_{|x-a|=\varepsilon} [\Delta (u - \frac{1}{4\pi|x-a|}) v - (u - \frac{1}{4\pi|x-a|}) \Delta v] dx = 0$$

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$$\textcircled{2} = \frac{1}{42\varepsilon} \int_{|x-a|=\varepsilon} \frac{dv}{dn} ds = \frac{1}{42\varepsilon} \int_{|x-a|=\varepsilon} \Delta v dx = 0$$

$$\textcircled{2} = \int_{|x-a|=\varepsilon} v \frac{\partial}{\partial r} \left( \frac{1}{42r} \right) ds = \frac{-1}{42\varepsilon^2} \int_{|x-a|=\varepsilon} v ds \rightarrow -v(a) = -G(b, a)$$

$$\left. \begin{array}{l} \text{即 } A_\varepsilon \rightarrow -G(b, a) \\ \text{同理 } B_\varepsilon \rightarrow G(a, b) \end{array} \right\} \Rightarrow G(a, b) = G(b, a)$$

若给出了 $\Omega$ 的表述, 则给出了 $\Omega$ 的表述, 下考虑 Green 函数求法

### 1. 半空间

$$\text{取 } X_0^* = (X_0^1, X_0^2, -X_0^3)$$

$$\text{def } G(x, X_0) = \frac{1}{42|x-X_0|} - \frac{1}{42|x-X_0^*|}$$

则 $G$ 满足 (1)(2)(3)

### 2. $B_R(0)$

$$G(x, X_0) = \frac{1}{42|x-X_0|} - \frac{C}{42|x-X_0^*|}$$

$X_0^*$  在球外, 此时 (1)(3) 自然满足

由 (2),  $\forall |x|=R$ , 有  $G(x, X_0) = 0$

$$\text{令 } |x-X_0| = \rho, |x-X_0^*| = \rho^* \Rightarrow \frac{\rho^*}{\rho} = C$$

$$\text{若 } \triangle_{小} \sim \triangle_{大}, \text{ 则 } \frac{\rho^*}{\rho} = \frac{|X_0^*|}{R} = \frac{R}{|X_0|}$$

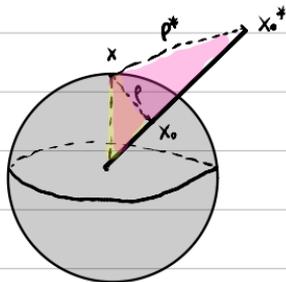
$$\text{取 } X_0^* \text{ 满足 } X_0^* = \frac{R^2}{|X_0|^2} X_0 \text{ 即可}$$

$$\text{则 } G(x, X_0) = \frac{1}{42|x-X_0|} - \frac{C}{42|x-X_0^*|}$$

$$C = \frac{R}{|X_0|}, X_0^* = \frac{R^2}{|X_0|^2} X_0 \text{ 即可}$$

将  $B_R(0)$  下的 Green 函数带入 (2.1),  $X \in \Omega$  时

$$\begin{aligned} \nabla G(x, X_0) &= -\frac{x-X_0}{42|x-X_0|^3} + \frac{C(x-X_0^*)}{42|x-X_0^*|^3} = -\frac{x-X_0}{42|x-X_0|^3} + \frac{|X_0|^2}{42R^2} \frac{x-X_0^*}{|x-X_0^*|^3} \\ &= -\frac{x}{42|x-X_0|^3} \left( 1 - \frac{|X_0|^4}{R^4} \right) + \frac{1}{42|x-X_0^*|^3} \left( X_0 - \frac{|X_0|^2}{R^2} X_0^* \right) = -\frac{x}{42|x-X_0|^3} \left( 1 - \frac{|X_0|^4}{R^4} \right) \end{aligned}$$



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$$\frac{\partial \phi}{\partial n} = n \cdot \nabla \phi = \frac{x}{|x|} \cdot \left( \frac{R^2 - |x_0|^2}{R^2} \frac{x}{4\pi|x-x_0|^3} \right) = \frac{R^2 - |x_0|^2}{R} \frac{1}{4\pi|x-x_0|^3}$$

$$\text{取 } u(x_0) = \frac{R^2 - |x_0|^2}{4\pi R} \int_{|x|=R} \frac{\phi(x)}{|x-x_0|^3} dS(x) \quad (\phi \text{ 为任意值})$$

$$\text{取 } u(x) = \frac{R^2 - x^2}{4\pi R} \int_{|y|=R} \frac{\phi(y)}{|x-y|^3} dS(y) \quad \text{Poisson 公式}$$

thm 4. (Harnack 不等式)

设  $u$  在  $B_R(x_0)$  内调和且  $u \geq 0$ , 则

$$\frac{R}{R+r} \frac{R-r}{R+r} u(x_0) \leq u(x) \leq \frac{R}{R-r} \frac{R+r}{R-r} u(x_0), \text{ 其中 } r = |x-x_0| < R$$

Remark. 2.1 中也有 Harnack 不等式, 均说明连通紧集中的任意两点函数值可互相比较, 区别在于该 thm 给出了具体的界

pr: 不妨设  $x_0 = 0$  (平移不变性)

则  $r = |x| < R$ , 只需证:

$$\frac{R}{R+r} \frac{R-r}{R+r} u(0) \leq u(x) \leq \frac{R}{R-r} \frac{R+r}{R-r} u(0)$$

$$\text{由 Poisson 公式, } u(x) = \frac{R^2 - x^2}{4\pi R} \int_{|y|=R} \frac{u(y)}{|x-y|^3} dS(y)$$

由于  $R-r \leq |x-y| \leq R+r$ , 则

$$\frac{R^2 - r^2}{4\pi R} \frac{1}{(R+r)^3} \int_{|y|=R} u(y) dS(y) \leq u(x) \leq \frac{R^2 - r^2}{4\pi R} \frac{1}{(R-r)^3} \int_{|y|=R} u(y) dS(y)$$

$u$  调和, 由平均值性质, 则  $\int_{|y|=R} u(y) dS(y) = 4\pi R^2 u(0)$

$$\frac{R(R^2 - r^2)}{(R+r)^3} u(0) \leq u(x) \leq \frac{R(R^2 - r^2)}{(R-r)^3} u(0) \quad \text{Pr: 证}$$

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n维情形下的推导:

$$\begin{cases} -\Delta u = 0 \\ u|_{\partial\Omega} = g \end{cases}$$

对  $u$  的基本解为  $v$ , 在  $\Omega \setminus B_\varepsilon(0) \doteq \Omega_\varepsilon$  上用第二 Green 公式

$$\int_{\Omega_\varepsilon} u \Delta v - v \Delta u \, dx = 0$$

$$= \int_{\partial\Omega_\varepsilon} u \frac{\partial v}{\partial n} - v \frac{\partial u}{\partial n} \, dS(x) = \int_{\partial\Omega} u \frac{\partial v}{\partial n} - v \frac{\partial u}{\partial n} \, dS(x) - \int_{\partial B(0,\varepsilon)} u \frac{\partial v}{\partial n} - v \frac{\partial u}{\partial n} \, dS(x)$$

$$\textcircled{1} \int_{\partial B(0,\varepsilon)} u \frac{\partial v}{\partial n} \, dS(x)$$

$$= \int_{\partial B(0,\varepsilon)} u \frac{\partial}{\partial n} \left( \frac{1}{n(n-2)\alpha(n)} \frac{1}{|x|^{n-2}} \right) \, dS(x)$$

$$= \int_{\partial B(0,\varepsilon)} u \frac{\partial}{\partial r} \left( \frac{1}{n(n-2)\alpha(n)} \frac{1}{r^{n-2}} \right) \, dS(x)$$

$$= \int_{\partial B(0,\varepsilon)} u \cdot \frac{1}{n(n-2)\alpha(n)} \frac{2-n}{r^{n-1}} \, dS(x)$$

$$= \frac{-1}{n\alpha(n)} \frac{1}{\varepsilon^{n-1}} \int_{\partial B(0,\varepsilon)} u \, dS(x) \rightarrow -u(0) \quad (\varepsilon \rightarrow 0)$$

$$\textcircled{2} \int_{\partial B(0,\varepsilon)} v \frac{\partial u}{\partial n} \, dS(x)$$

$$= \int_{\partial B(0,\varepsilon)} \frac{1}{n(n-2)\alpha(n)} \frac{1}{|x|^{n-2}} \frac{\partial u}{\partial n} \, dS(x)$$

$$= \frac{1}{n(n-2)\alpha(n)} \frac{1}{|\varepsilon|^{n-2}} \int_{B(0,\varepsilon)} \Delta u \, dx = 0$$

$$\text{故 } u(0) = \int_{\partial\Omega} -u \frac{\partial v}{\partial n} + v \frac{\partial u}{\partial n} \, dS(x)$$

$$\text{若 } -\Delta u = f, \text{ 则 } \int_{\partial B(0,\varepsilon)} v \frac{\partial u}{\partial n} \, dS(x) = \frac{1}{n(n-2)\alpha(n)} \frac{-1}{|\varepsilon|^{n-2}} \int_{B(0,\varepsilon)} f \, dx$$

$$\text{再 } \int_{\Omega_\varepsilon} v f \, dx = \int_{\partial\Omega} u \frac{\partial v}{\partial n} - v \frac{\partial u}{\partial n} \, dS(x) + u(0) + \frac{1}{n(n-2)\alpha(n)} \frac{-1}{|\varepsilon|^{n-2}} \int_{B(0,\varepsilon)} f \, dx$$

$$\Rightarrow u(0) = \int_{\partial\Omega} -u \frac{\partial v}{\partial n} + v \frac{\partial u}{\partial n} \, dS(x) + \int_{\Omega_\varepsilon} v f \, dx + \frac{1}{n(n-2)\alpha(n)} \frac{1}{|\varepsilon|^{n-2}} \int_{B(0,\varepsilon)} f \, dx$$

$$= \int_{\partial\Omega} -u \frac{\partial v}{\partial n} + v \frac{\partial u}{\partial n} \, dS(x) + \int_{\Omega} v f \, dx$$

$$\Leftrightarrow u(x) = \int_{\Omega} f(y) \Gamma(x-y) \, dy - \int_{\partial\Omega} g(y) \frac{\partial \Gamma}{\partial n}(x-y) + \int_{\partial\Omega} \frac{\partial u}{\partial n}(y) \Gamma(x-y) \, dS(y)$$

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用  $\bar{G}(x, y) \equiv \Gamma(x-y) - \phi^*(y)$  代替  $\Gamma(x-y)$

要求  $\bar{G}|_{\partial\Omega} = 0, \Delta \bar{G}(x, y) = 0$

$$\begin{array}{ccc} \downarrow & & \downarrow \\ \phi^*(y)|_{\partial\Omega} = \Gamma(x-y) & & \Delta \phi^*(y) = 0 \end{array}$$

$$u(x) = \int_{\Omega} f(y) \bar{G}(x-y) dy - \int_{\partial\Omega} \frac{\partial \bar{G}}{\partial n}(x, y) g(y) dS(y)$$

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## §2.3 极值原理和最大模估计

考虑方程  $\mathcal{L}u = -\Delta u + c(x)u = f(x)$ ,  $c(x) \geq 0$ ,  $x \in \Omega$

### thm 1. 弱极大值原理

$c(x) \geq 0$ ,  $f(x) < 0$ .  $u \in C^2(\Omega) \cap C(\bar{\Omega})$ , 且满足以上方程, 则

$u(x)$  不能在  $\Omega$  上达到它在  $\bar{\Omega}$  上的非负最大值,

即  $u(x)$  只能在  $\partial\Omega$  上达到非负最大值

(注意, 并不意味着在边界上一定能取到非负最大值)

pr: 假设  $u$  在  $x_0 \in \Omega$  达到非负最大值  $M \geq 0$

则  $(\nabla u)(x_0) = 0$ ,  $(\Delta u)(x_0) = \text{tr}(\text{Hesse } u(x_0)) \leq 0$

$(\mathcal{L}u)(x_0) = -\Delta u(x_0) + c(x_0)u(x_0) \geq 0$  与  $f(x) < 0$  矛盾

### thm 2.

$c(x) \geq 0$ ,  $f(x) \leq 0$ .  $u \in C^2(\Omega) \cap C(\bar{\Omega})$ , 且满足以上方程

且在  $\bar{\Omega}$  上存在正的最大值, 则  $u(x)$  必在  $\partial\Omega$  上达到在  $\bar{\Omega}$  上的非负最大值

且  $\max_{x \in \bar{\Omega}} u(x) \leq \max_{\partial\Omega} u^+(x)$

$u^+ = \max\{u(x), 0\}$

pr: 不妨设  $0 \in \Omega$ , 令  $d = \text{diam } \Omega$ .

令  $v(x) = -(d^2 - |x|^2) \leq 0$   $u^\varepsilon(x) = u(x) + \varepsilon v(x)$

$\mathcal{L}u^\varepsilon = \mathcal{L}u + \varepsilon \mathcal{L}v = f + \varepsilon(-\Delta(d^2 - |x|^2) + c(x)(d^2 - |x|^2))$

$= f - 2\varepsilon + \varepsilon c(x)(-d^2 + |x|^2) < 0$

应用 thm 1.

$\max_{\bar{\Omega}} u - \varepsilon d^2 = \max_{\bar{\Omega}} (u - \varepsilon d^2) \leq \max_{\bar{\Omega}} u_\varepsilon \leq \max_{\partial\Omega} (u + \varepsilon v)^+ \leq \max_{\partial\Omega} u^+$

令  $\varepsilon \rightarrow 0$ .  $\max_{\bar{\Omega}} u \leq \max_{\partial\Omega} u^+$

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Rmk. 若  $u$  在  $\Omega$  上最大值为负数, 与 thm 1.2 无关

下面我们应证明强极大值原理.

thm 3. (Hopf 引理)

设  $B_R$  为  $\mathbb{R}^n$  ( $n=2,3$ ) 上以  $R$  为半径的球, 在  $B_R$  上  $c(x) \geq 0$  有界,

若  $u \in C^2(B_R) \cap C^1(\bar{B}_R)$  满足

$$(1) \Delta u = -\Delta u + c(x)u \leq 0, \quad x \in B_R$$

(2)  $\exists x_0 \in \partial B_R$ , st.  $u$  在  $x_0$  处达到  $\bar{B}_R$  上的非负最大值

即  $u(x_0) = \max_{\bar{B}_R} u \geq 0$  且当  $x \in B_R$  时,  $u(x) < u(x_0)$ .

则

$\frac{\partial u}{\partial \bar{n}} \Big|_{x=x_0} > 0$ ,  $\mu$  与  $\partial B_R$  在  $x_0$  点单位外法向量  $n$  夹角小于  $\frac{\pi}{2}$

pr: 由 (1) 易知  $\frac{\partial u}{\partial \bar{n}} \Big|_{x=x_0} \geq 0$

$$\text{令 } v(x) = e^{-\alpha|x|^2} - e^{-\alpha R^2} \quad \alpha > 0 \text{ 待定}$$

$$w(x) = u(x) - u(x_0) + \varepsilon v(x) \quad \varepsilon > 0$$

$$\nabla v = e^{-\alpha|x|^2} \cdot (-2\alpha \bar{x})$$

$$\begin{aligned} \Delta v &= \sum_i \partial x_i (-2\alpha x_i e^{-\alpha|x|^2}) = \sum (-2\alpha + 4\alpha^2 x_i^2) e^{-\alpha|x|^2} \\ &= (-2\alpha n + 4\alpha^2 |x|^2) e^{-\alpha|x|^2} \end{aligned}$$

$$\Delta w = \Delta u - c(x)u(x_0) + \varepsilon \Delta v$$

$$= \Delta u - c(x)u(x_0) + \varepsilon [(-4|\alpha|^2|x|^2 + 2\alpha n) e^{-\alpha|x|^2} + c(x)(e^{-\alpha|x|^2} - e^{-\alpha R^2})]$$

$$= \Delta u - c(x)u(x_0) + \varepsilon \left[ \underbrace{(-4|\alpha|^2|x|^2 + 2\alpha n)}_{\leq 0} + \underbrace{c(x)}_{\geq 0} \right] e^{-\alpha|x|^2} - \underbrace{c(x)}_{\geq 0} \varepsilon e^{-\alpha R^2}$$

$$\leq \varepsilon (-4|\alpha|^2|x|^2 + 2\alpha n + c) e^{-\alpha|x|^2} \quad c \text{ 为 } c(x) \text{ 的界}$$

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在  $B_R^* = \{ \frac{R}{2} \leq |x| \leq R \}$  上做估计,

$$\leq \varepsilon (-R^2 \alpha^2 + 2\alpha n + c) e^{-\alpha |x|^2}$$

$< 0$  ( $\alpha$  充分大)

由 thm 1, 在  $B_R^*$  对  $w$  应用极大值原理,

$w$  在  $\bar{B}_R$  上的非负最大值必在边界上取到

$$|x| = \frac{R}{2} \text{ 时, } w(x) = u(x) - u(x_0) + \varepsilon (e^{-\alpha \frac{R^2}{4}} - e^{-\alpha R^2})$$

$$\Rightarrow w(x) \leq \max_{|x| = \frac{R}{2}} u(x) - u(x_0) + \varepsilon (e^{-\alpha \frac{R^2}{4}} - e^{-\alpha R^2})$$

$< 0$  ( $\varepsilon$  充分小)

$|x| = R$  时,  $w(x)$  在  $x_0$  处取得最大值

$$\Rightarrow \frac{\partial w}{\partial \mu} \geq 0$$

$$\text{即 } \frac{\partial u}{\partial \mu} + \varepsilon \frac{\partial v}{\partial \mu} \geq 0$$

$$\text{而 } \frac{\partial v}{\partial \mu} = \mu \cdot \nabla v = \mu \cdot e^{-\alpha |x|^2} (-2\alpha \bar{x}) < 0$$

$$\Rightarrow \frac{\partial u}{\partial \mu} > 0$$

#### thm 4. 强极大值原理

假设  $\Omega$  为  $\mathbb{R}^n$  中有界 连通开集,  $u(x) \geq 0$  有界

若  $u \in C^2(\Omega) \cap C(\bar{\Omega})$  在  $\Omega$  上满足  $\Delta u \leq 0$ , 且  $u$  在  $\Omega$  内达到在  $\bar{\Omega}$  上非负最大值, 则  $u$  在  $\bar{\Omega}$  上恒为常数.

pr: 令  $M = \max_{x \in \bar{\Omega}} u(x) \geq 0$ , 令  $O = \{x \in \Omega \mid u(x) = M\}$ , 即证  $O = \bar{\Omega}$

step 1.  $O \neq \emptyset$

step 2.  $O$  闭. 即  $x_n \in O, x_n \rightarrow \bar{x}$ , 则  $\bar{x} \in O$

$u$  连续, 则  $u(\bar{x}) = \lim_{n \rightarrow \infty} u(x_n) = M$ , 则  $\bar{x} \in O$

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Step 3. 0开.

若不为开集, 则  $\exists x_0 \in \Omega \setminus 0$  ( $\Omega$ 开而 $0$ 不开,  $0 \subseteq \Omega$ )

$\Omega \setminus 0$ 开,  $\exists R > 0$ , st.  $B_R(x_0)$ 与 $\partial\Omega$ 相切于 $y_0$ .

claim: ①  $u$ 在 $y_0$ 达到 $\bar{\Omega}$ 上的非负最大值

$$\textcircled{2} \forall x \in B_R(x_0), u(x) < M$$

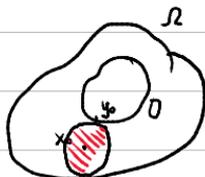
由Hopf引理,  $\frac{\partial u}{\partial \nu}(y_0) > 0$

( $y_0 \in \Omega$ , 由于 $\Omega^c \cap 0 = \emptyset$ ,  $\Omega^c \cdot 0$ 同闭,  $\text{dist}(\Omega^c, 0) > 0$ )

而 $y_0 \in \Omega$ 达到最大值,  $\nabla u(y_0) = 0$ ,  $\frac{\partial u}{\partial \nu}(y_0) = 0$ 矛盾

则 $0$ 为开集

结合1.2.3知 $0 = \Omega$



Rm. ① 若 $-\Delta u < 0$ , 则 $u$ 只在边界处达到最大值.

(若在 $x_0 \in \Omega$ 处达到, 则 $-\Delta u(x_0) \geq 0$ 矛盾)

② 若 $u$ 调和 ( $u \in C(\bar{\Omega})$  满足平均值性质), 则 $u$ 只在 $\partial\Omega$ 达到最大值和最小值, 除非 $u$ 为常数 (即若最大值/最小值在内部取到, 则必为常数)

pr: 不妨最大值在内部取到, 设 $M = \max_{\bar{\Omega}} u(x)$

$$\text{令 } 0 = \{x \in \Omega \mid u(x) = M\}, 0 \text{ 非空闭}$$

只需证 $0$ 为开集

$\forall x_0 \in 0, \exists B_R(x_0) \subseteq \Omega$ , 由平均值性质

$$M = u(x_0) = \frac{1}{|B_R(x_0)|} \int_{B_R(x_0)} u(y) dy \leq M$$

$$\Rightarrow u(x) \equiv M, x \in B_R(x_0), \text{ 则 } B_R(x_0) \subseteq 0$$

故 $0$ 为开集

①②表明 $\Delta u \geq 0$ , 则只能在边界处达到最大值, 无非负性要求.

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## 下利用极值原理证明最大模估计.

$$\text{考虑 } \begin{cases} -\Delta u = f & \text{in } \Omega \\ u = g & \text{on } \partial\Omega \end{cases} \quad (2.41)$$

### thm 5. 最大模估计

$u \in C^2(\Omega) \cap C(\bar{\Omega})$  为 (2.41) 的解, 则

$$\max_{\bar{\Omega}} |u(x)| \leq G + CF, \quad G = \max_{\partial\Omega} |g|, \quad F = \max_{\bar{\Omega}} |f|, \quad C = C(n, \text{diam}(\Omega))$$

idea.  $\Delta u \geq 0, u|_{\partial\Omega} \leq 0 \Rightarrow u \leq 0$

pr: 不妨  $0 \in \Omega, \forall x \in \Omega, |x| < d$

$$\text{令 } w(x) = u - \left(G + \frac{F}{2n} (d^2 - |x|^2)\right)$$

$$\text{则 } -\Delta w = -\Delta u - F = f - F \leq 0$$

$$w|_{\partial\Omega} = g - G - \frac{F}{2n} (d^2 - |x|^2) \leq g - G \leq 0$$

由弱极值原理,  $\max_{\bar{\Omega}} w - \max_{\partial\Omega} w \leq 0$

$$0 \geq \max_{\bar{\Omega}} \left( u(x) - \left(G + \frac{F}{2n} d^2\right) + \frac{F}{2n} |x|^2 \right) \geq \max_{\bar{\Omega}} u(x) - \left(G + \frac{F}{2n} d^2\right)$$

$$\Rightarrow u(x) \leq G + \frac{d^2}{2n} F$$

$$\text{再令 } \tilde{w}(x) = -u - \left(G + \frac{F}{2n} (d^2 - |x|^2)\right)$$

$$\text{则 } -\Delta \tilde{w} = -f - F \leq 0$$

$$\tilde{w}|_{\partial\Omega} \leq -g - G \leq 0$$

由弱极值原理,  $\max_{\bar{\Omega}} \tilde{w} - \max_{\partial\Omega} \tilde{w} \leq 0$

$$\Rightarrow -u(x) \leq G + \frac{d^2}{2n} F$$

$$\text{故 } |u(x)| \leq G + \frac{d^2}{2n} F \quad \forall x \in \Omega.$$

Rmk. 最大模估计蕴含解的唯一性与稳定性.

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设  $u_1, u_2$  为 (2.41) 的解, 设  $v = u_1 - u_2$

$$\begin{cases} -\Delta v = 0 \\ v|_{\partial\Omega} = 0 \end{cases}$$

由最大模估计  $\max_{\bar{\Omega}} |v(x)| \leq 0 + C \cdot 0 = 0 \Rightarrow u_1 = u_2$ , 即唯一性

设  $u_1, u_2$  为

$$\begin{cases} -\Delta u = f_1 \\ u|_{\partial\Omega} = g_1 \end{cases} \quad \text{与} \quad \begin{cases} -\Delta u = f_2 \\ u|_{\partial\Omega} = g_2 \end{cases}$$

的解

由最大模估计  $\max_{\bar{\Omega}} |u_1(x) - u_2(x)| \leq \max_{\partial\Omega} |g_1 - g_2| + C \max_{\bar{\Omega}} |f_1 - f_2|$

蕴含稳定性

唯一性与稳定性可通过能量法给出

$$\text{考虑方程} \begin{cases} -\Delta u = f & \text{in } \Omega \\ u = 0 & \text{on } \partial\Omega \end{cases}$$

$$\int_{\Omega} u(-\Delta u) dx = \int_{\Omega} f u dx = \int_{\Omega} -\operatorname{div}(u \nabla u) + |\nabla u|^2 dx = -\int_{\partial\Omega} u \frac{\partial u}{\partial n} dS + \int_{\Omega} |\nabla u|^2 dx$$

claim. (Friedrichs 不等式)

$$u \in C_0^1(\Omega), \text{ 则 } \int_{\Omega} |u(x)|^2 dx \leq 4d^2 \int_{\Omega} |\nabla u(x)|^2 dx \quad d = \operatorname{diam}(\Omega)$$

$$\text{则 } \int_{\Omega} f u dx \leq \varepsilon \int_{\Omega} |u|^2 dx + \frac{1}{4\varepsilon} \int_{\Omega} |f|^2 dx$$

$$\int_{\Omega} |\nabla u|^2 dx \leq \varepsilon \cdot 4d^2 \int_{\Omega} |\nabla u|^2 dx + \frac{1}{4\varepsilon} \int_{\Omega} |f|^2 dx$$

$$\text{选取合适的 } \varepsilon \text{ 可 st. } \int_{\Omega} |\nabla u|^2 dx \leq C \int_{\Omega} |f|^2 dx$$

Rmk. 该表达式蕴含  $|\nabla u|, |u|$  的控制, Poisson 方程的能量为右端项与  $u$ .

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## 第三章 热传导方程

$$u_t - \Delta u = f(x, t) \quad x \in \Omega, t > 0$$

$$u(x, 0) = \varphi(x)$$

$$\text{(Dirichlet)} \quad u|_{\partial\Omega} = g(x, t)$$

$$\text{(Neumann)} \quad \frac{\partial u}{\partial n}|_{\partial\Omega} = g(x, t)$$

$$\text{(Robin)} \quad \frac{\partial u}{\partial n} + \sigma u|_{\partial\Omega} = g(x, t)$$

$u$  表示温度 etc, 描述传热过程、扩散过程;

$f$  表示热源.

### §3.1 初值问题

解法1 分离变量法

$\Omega = [0, 1]$ , 矩形区域, 圆盘 etc.

解法2. Fourier 变换法

$$\text{考察方程} \begin{cases} u_t - \Delta u = f(x, t) & x \in \mathbb{R}^n, t > 0 \\ u(x, 0) = \varphi(x) \end{cases}$$

Recall. ( $\mathbb{R}^n$  上的 Fourier 变换)

$$f \in \mathcal{L}^1(\mathbb{R}^n), \left( \int_{\mathbb{R}^n} |f(x)| dx < +\infty \right)$$

$$\text{def. } \hat{f}(\xi) = \int_{\mathbb{R}^n} f(x) e^{-2\pi i x \cdot \xi} dx$$

性质  $f \in \mathcal{S}(\mathbb{R}^n)$ , ( $f$  光滑,  $\forall$  阶导数衰减任意快)

则不考虑分部积分边界项

$$1. \text{ 令 } (\tau_{x_0} f)(x) = f(x - x_0), \text{ 则 } \widehat{(\tau_{x_0} f)}(\xi) = e^{-2\pi i x_0 \cdot \xi} \hat{f}(\xi)$$

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$$\begin{aligned} \text{pr. } \widehat{T_{x_0} f}(\xi) &= \int_{\mathbb{R}^n} f(x-x_0) e^{-2zi(x-\xi)} dx \\ &= \int_{\mathbb{R}^n} f(y) e^{-2zi(x_0+y)\xi} dy \\ &= e^{-2zi x_0 \xi} \int_{\mathbb{R}^n} f(y) e^{-2zi y \xi} dy \\ &= e^{-2zi x_0 \xi} \widehat{f}(\xi) \end{aligned}$$

2. 令  $(S_\lambda f)(x) = f(\lambda x)$ , 则  $\widehat{S_\lambda f}(\xi) = \lambda^{-n} \widehat{f}(\lambda^{-1}\xi)$

$$\begin{aligned} \text{pr. } \widehat{S_\lambda f}(\xi) &= \int_{\mathbb{R}^n} f(\lambda x) e^{-2zi x \cdot \xi} dx \\ &= \int_{\mathbb{R}^n} f(y) e^{-2zi \frac{y}{\lambda} \cdot \xi} \lambda^{-n} dy \\ &= \lambda^{-n} \int_{\mathbb{R}^n} f(y) e^{-2zi y \cdot \frac{\xi}{\lambda}} dy \\ &= \lambda^{-n} \int_{\mathbb{R}^n} \widehat{f}(\lambda^{-1}\xi) \end{aligned}$$

3. 对多重指标  $\alpha = (\alpha_1, \dots, \alpha_n)$ , 记  $|\alpha| = \alpha_1 + \dots + \alpha_n$ ,  $X^\alpha = x_1^{\alpha_1} \dots x_n^{\alpha_n}$

$$\partial^\alpha = \partial_{x_1}^{\alpha_1} \dots \partial_{x_n}^{\alpha_n}, \text{ 则 } \widehat{\partial^\alpha f}(\xi) = (2zi\xi)^\alpha \widehat{f}(\xi)$$

$$\begin{aligned} \text{pr. } \widehat{\partial_{x_j} f}(\xi) &= \int_{\mathbb{R}^n} \partial_{x_j} f(x) e^{-2zi x \cdot \xi} dx \\ &= - \int_{\mathbb{R}^n} f(x) e^{-2zi x \cdot \xi} (-2zi\xi_j) dx \\ &= 2zi\xi_j \int_{\mathbb{R}^n} f(x) e^{-2zi x \cdot \xi} dx \\ &= 2zi\xi_j \widehat{f}(\xi) \end{aligned}$$

$$4. (-2zi\xi)^\alpha \widehat{f}(\xi) = \partial_\xi^\alpha \widehat{f}(\xi)$$

$$\begin{aligned} \text{pr. } (-2zi\xi_j)^\alpha \widehat{f}(\xi) &= \int_{\mathbb{R}^n} -2zi\xi_j f(x) e^{-2zi x \cdot \xi} dx \\ &= \int_{\mathbb{R}^n} (e^{-2zi x \cdot \xi})_{\xi_j} f(x) dx \\ &= \partial_{\xi_j} \int_{\mathbb{R}^n} f(x) e^{-2zi x \cdot \xi} dx \\ &= \partial_{\xi_j} \widehat{f}(\xi) \end{aligned}$$

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$$5. \text{ 令 } (f * g)(x) = \int_{\mathbb{R}^n} f(x-y)g(y)dy = \int_{\mathbb{R}^n} f(y)g(x-y)dy$$

$$\forall f, g \in \mathcal{S}(\mathbb{R}^n), \text{ 则 } \widehat{f * g}(\xi) = \widehat{f}(\xi) \widehat{g}(\xi)$$

6. 傅里叶变换

$$f(x) = \int_{\mathbb{R}^n} \widehat{f}(\xi) e^{2\pi i x \cdot \xi} d\xi, \text{ 则若 } f \in \mathcal{S}(\mathbb{R}^n), \text{ 有}$$

$$\widehat{f} \in \mathcal{S}(\mathbb{R}^n), \widehat{\widehat{f}} = f$$

$$\text{例. 若 } f(x) = e^{-x^2}, x \in \mathbb{R}, \text{ 则 } \widehat{f}(\xi) = \sqrt{\pi} e^{-\pi^2 \xi^2}$$

$$\text{令 } F(\xi) = \widehat{f}(\xi) = \int_{\mathbb{R}} e^{-x^2} e^{-2\pi i x \xi} dx$$

$$F'(\xi) = \int_{\mathbb{R}} e^{-x^2} (-2\pi i x) e^{-2\pi i x \xi} dx$$

$$= 2\pi i \int_{\mathbb{R}} (e^{-x^2})' e^{-2\pi i x \xi} dx$$

$$= 2\pi i \widehat{f}'(\xi) = 2\pi i \cdot 2\pi i \xi \widehat{f}(\xi)$$

$$= -2\pi^2 \xi F(\xi)$$

$$F(0) = \int_{\mathbb{R}} e^{-x^2} dx = \sqrt{\pi}$$

$$\Rightarrow F(\xi) = \sqrt{\pi} \int_{-\infty}^{\xi} -2\pi^2 \xi d\xi = \sqrt{\pi} e^{-\pi^2 \xi^2}$$

$$\text{注: } f(x) \in \mathcal{S}(\mathbb{R}), \text{ 则 } (e^{-\pi^2 x^2})'(x) = \frac{1}{\sqrt{\pi}} e^{-x^2}$$

$$(e^{-4\pi^2 x^2})'(x) = \frac{1}{2\sqrt{\pi}} e^{-\frac{x^2}{4}}$$

$$n \geq 1 \text{ 时, } (e^{-4\pi^2 |x|^n t})'(x) = \prod_{j=1}^n (e^{-4\pi^2 x_j^2 t})'(x_j) = \prod_{j=1}^n \frac{1}{2\sqrt{\pi}} e^{-\frac{x_j^2}{4}} = \frac{1}{(2\sqrt{\pi})^n} e^{-\frac{|x|^2}{4}}$$

回到热传导方程的解.

$$\text{对方程 } \begin{cases} u_t - \Delta u = 0 & x \in \mathbb{R}^n, t > 0 \\ u|_{t=0} = \varphi(x) & x \in \mathbb{R}^n \end{cases}$$

$$\text{两边关于 } x \text{ 作 Fourier 变换, 则 } \begin{cases} \partial_t \widehat{u}(\xi) + 4\pi^2 |\xi|^2 \widehat{u}(\xi) = 0 \\ \widehat{u}(\xi)|_{t=0} = \widehat{\varphi}(\xi) \end{cases}$$

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$$\Rightarrow \hat{u}(s, t) = \hat{\varphi}(s) e^{-4s^2 |s|^2 t}$$

做逆变换, 由性质  $f * g = (\hat{f} \hat{g})^\vee = \hat{f}^\vee * \hat{g}^\vee$  (相乘的逆变换 = 逆变换的卷积)

$$\Rightarrow u(x, t) = (e^{-4s^2 |s|^2 t})^\vee * \varphi$$

$$= \frac{1}{(4t)^{\frac{n}{2}}} e^{-\frac{|x|^2}{4t}} * \varphi$$

$$= \frac{1}{(4t)^{\frac{n}{2}}} \int_{\mathbb{R}^n} e^{-\frac{|x-y|^2}{4t}} \varphi(y) dy$$

貌似在  $t=0$  有奇性, 这说明  $t=0$  时满足初值

$$\text{令 } k(x) = \frac{1}{(4t)^{\frac{n}{2}}} e^{-\frac{|x|^2}{4t}} \quad (\text{Heat kernel})$$

$$k_t(x) = t^{-\frac{n}{2}} k(t^{-\frac{1}{2}}x), \quad t > 0$$

$$\text{则 } u(x, t) = \int_{\mathbb{R}^n} k_t(x-y) \varphi(y) dy = \int_{\mathbb{R}^n} k_t(y) \varphi(x-y) dy$$

$$\{k_t\}_{t>0} \text{ 有: (i) } \int_{\mathbb{R}^n} k_t(x) dx = \int_{\mathbb{R}^n} k(x) dx = 1$$

$$\text{左} = \int_{\mathbb{R}^n} t^{-\frac{n}{2}} k(t^{-\frac{1}{2}}x) dx = \int_{\mathbb{R}^n} k(y) dy = \frac{1}{(4t)^{\frac{n}{2}}} \int_{\mathbb{R}^n} e^{-\frac{|y|^2}{4t}} dx = 1$$

$$(\int_{\mathbb{R}^n} e^{-x^2} dx = \sqrt{\pi})$$

$$(ii) \int_{\mathbb{R}^n} |k_t(x)| dx = 1$$

$$(iii) \forall \eta > 0, \int_{|x|>\eta} k_t(x) dx = \int_{|y|>\frac{\eta}{\sqrt{t}}} k(y) dy \rightarrow 0 \quad (t \rightarrow 0^+)$$

$\{k_t\}_{t>0}$  为一族逼近恒等算子

$$u(x, t) = k_t * \varphi \xrightarrow{t \rightarrow 0^+} \varphi \quad \varphi \in C(\mathbb{R}^n), \text{ 有界}$$

$$|u(x, t) - \varphi(x)| = \left| \int_{\mathbb{R}^n} k_t(y) \varphi(x-y) dy - \int_{\mathbb{R}^n} k_t(y) \varphi(x) dy \right|$$

$$= \left| \int_{\mathbb{R}^n} k_t(y) (\varphi(x-y) - \varphi(x)) dy \right|$$

$$\leq \frac{1}{(4t)^{\frac{n}{2}}} \int_{\mathbb{R}^n} e^{-\frac{|y|^2}{4t}} |\varphi(x-y) - \varphi(x)| dy$$

$$= \frac{1}{(4t)^{\frac{n}{2}}} \int_{\mathbb{R}^n} e^{-\frac{|z|^2}{4t}} |\varphi(x - z\sqrt{t}) - \varphi(x)| dz$$

$$z = \frac{y}{\sqrt{t}}$$

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$$① = \frac{1}{(4t)^{\frac{n}{2}}} \int_{|z| > R} e^{-\frac{|z|^2}{4t}} |\varphi(x-\sqrt{t}z) - \varphi(x)| dz \leq \frac{1}{(4t)^{\frac{n}{2}}} \int_{|z| > R} e^{-\frac{|z|^2}{4t}} dz \cdot 2\|\varphi\|_{C^0} \rightarrow 0 \quad (R \text{ 充分大})$$

$$② = \frac{1}{(4t)^{\frac{n}{2}}} \int_{|z| < R} e^{-\frac{|z|^2}{4t}} |\varphi(x-\sqrt{t}z) - \varphi(x)| dz$$

由于  $\varphi$  连续, 有  $\forall |z| < R, |\varphi(x-\sqrt{t}z) - \varphi(x)| < \varepsilon, t \rightarrow 0^+$

则 ②  $\leq C\varepsilon \Rightarrow |u(x, t) - \varphi(x)| \rightarrow 0, t \rightarrow 0^+$

Rmk. 1. 由  $u$  的光滑性 (以及  $u(x, t) = k_0(x) * \varphi$ ) 表明  $u$  具有光滑性

$$2. \sup_x |u(x, t)| \leq \sup_x |\varphi(x)|$$

$$\text{由于 } u(x, t) = \frac{1}{(4t)^{\frac{n}{2}}} \int_{\mathbb{R}^n} e^{-\frac{|x-y|^2}{4t}} \varphi(x-y) dy$$

$$\sup_x |u(x, t)| \leq \frac{1}{(4t)^{\frac{n}{2}}} \int_{\mathbb{R}^n} e^{-\frac{|y|^2}{4t}} \sup_x |\varphi(x)| dy = \sup_x |\varphi(x)|$$

即温度最大值小于初始最大值, 同时  $t$  足够大时  $u(x, t) \rightarrow 0$  (衰减)

3. 热方程随时间不反向演化, 即从未态无法推及初态

4. 无限传播速度,  $\forall$  位置  $x$  的  $u(x, t) > 0$

**齐次非齐次方程**

$$\text{对方程 } \begin{cases} u_t - \Delta u = f(x, t) & x \in \mathbb{R}^n, t > 0 \\ u(x, 0) = \varphi(x) & x \in \mathbb{R}^n \end{cases}$$

$$\text{取 Fourier 变换, 有 } \begin{cases} \partial_t \hat{u} + 4t^2 |\xi|^2 \hat{u} = \hat{f}(\xi, t) \\ \hat{u}(\xi, 0) = \hat{\varphi}(\xi) \end{cases}$$

$$\Rightarrow \hat{u}(\xi, t) = \hat{\varphi}(\xi) e^{-4t^2 |\xi|^2 t} + \int_0^t e^{-4t^2 |\xi|^2 (t-s)} \hat{f}(\xi, s) ds$$

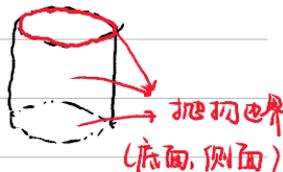
取 Fourier 逆变换, 有

$$u(x, t) = \frac{1}{(4t)^{\frac{n}{2}}} \int_{\mathbb{R}^n} e^{-\frac{|x-y|^2}{4t}} \varphi(y) dy + \int_0^t \frac{1}{(4t(t-s))^{\frac{n}{2}}} \int_{\mathbb{R}^n} e^{-\frac{|x-y|^2}{4t(t-s)}} f(y, s) dy ds$$

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### §3.2 极值原理和最大模估计

$$\text{考虑 } \begin{cases} u_t - \Delta u = 0 & \text{in } \Omega \times \{t > 0\} \\ u|_{t=0} = \varphi(x) & \text{in } \Omega \\ u(x, t) = h(x, t) & \text{on } \partial\Omega \times \{t > 0\} \end{cases}$$



令  $\Omega_T = \Omega \times (0, T]$ , 定义抛物面边界  $\Gamma_T = \overline{\Omega_T} \setminus \Omega_T$

#### thm 1. 极值原理

$u \in C^{2,1}(\Omega_T) \cap C(\overline{\Omega_T})$  满足  $\mathcal{L}u \equiv u_t - \Delta u = f \leq 0$

则  $u(x, t)$  在  $\overline{\Omega_T}$  上最大值必在  $\Gamma_T$  上达到, 即

$$\max_{\overline{\Omega_T}} u(x, t) = \max_{\Gamma_T} u(x, t)$$

$$\text{pr: 令 } M = \max_{\overline{\Omega_T}} u(x, t), m = \min_{\Gamma_T} u(x, t)$$

step 1.  $f < 0$ , 若  $M > m$ ,

则  $f$  在  $(x_0, t_0) \in \Omega_T$  上达到最大值

则  $u_{xx}(x_0, t_0) \leq 0, u_t(x_0, t_0) \geq 0$

$\mathcal{L}u(x_0, t_0) = u_t(x_0, t_0) - \Delta u(x_0, t_0) \geq 0$  矛盾

step 2.  $f = 0$ , 令  $v = u - \varepsilon t$ , 则  $\mathcal{L}v = \mathcal{L}u - \varepsilon = f - \varepsilon < 0$

由 step 1.

$$\max_{\overline{\Omega_T}} u - \varepsilon T \leq \max_{\overline{\Omega_T}} v = \max_{\Gamma_T} v \leq \max_{\Gamma_T} u$$

由  $\varepsilon$  的任意性,  $\max_{\overline{\Omega_T}} u = \max_{\Gamma_T} u$

Rank. 则  $\mathcal{L}u = f \geq 0$ , 则  $u$  在  $\overline{\Omega_T}$  上最小值, 必在边界处取到

#### thm 2. 比较原理

$u, v \in C^{2,1}(\Omega_T) \cap C(\overline{\Omega_T})$  满足  $\mathcal{L}u \leq \mathcal{L}v, u|_{\partial\Omega_T} \leq v|_{\partial\Omega_T}$ , 则在  $\overline{\Omega_T}, u(x, t) \leq v(x, t)$

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pr: 令  $w(x, t) = u(x, t) - v(x, t)$

$$Lw = Lu - Lv \leq 0, \quad w|_{\partial Q_T} \leq 0$$

故由极值原理,  $\max_{\bar{Q}_T} w = \max_{\partial Q_T} w$

$$\text{则 } u(x, t) \leq v(x, t) \quad \forall (x, t) \in \bar{Q}_T$$

### thm 3. 最大模估计

设  $u \in C^2(\bar{Q}_T) \cap C(\bar{Q}_T)$  为方程  $\begin{cases} Lu = f, & x \in (0, l) \times \{t > 0\} \\ u|_{t=0} = \varphi(x) & x \in [0, l] \\ u|_{x=0} = g_1(t) & u|_{x=l} = g_2(t) \end{cases}$

的解, 则

$$\max_{\bar{Q}_T} |u(x, t)| \leq Ft + B$$

$$F = \max_{\bar{Q}_T} |f|, \quad B = \max \left\{ \max_{x \in [0, l]} |\varphi(x)|, \max_{[0, T]} |g_1(t)|, \max_{[0, T]} |g_2(t)| \right\}$$

pr:  $v = Ft + B - u$

$$\begin{cases} Lv = F - f \geq 0 \\ v|_{\partial Q_T} = Ft + B - g_1/g_2 \geq 0 \end{cases}$$

由极大值原理,  $\min_{\bar{Q}_T} v = \min_{\partial Q_T} v \geq 0$

$$\Rightarrow v(x, t) \geq 0 \quad \forall (x, t) \in \bar{Q}_T$$

$$\text{则 } u(x, t) \leq Ft + B$$

对  $v = Ft + B + u$  完成相同过程  $\Rightarrow -u(x, t) \leq Ft + B$

$$\Rightarrow |u(x, t)| \leq Ft + B \leq Ft + B$$

Rmk. 可证明热方程解的唯一性、稳定性

下考虑其余两类边值问题解的唯一性与稳定性

第三类边值问题

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$$\begin{cases} u_t - u_{xx} = f(x, t) \\ u(0, t) = \mu_1(t) \quad u_x + hu(l, t) = \mu_2(t) \quad h > 0 \\ u(x, 0) = \varphi(x) \end{cases}$$

pr: 只需证明  $\begin{cases} u_t - u_{xx} = 0 \\ u(0, t) = 0 \quad u_x + hu(l, t) = 0 \quad h > 0 \\ u(x, 0) = 0 \end{cases}$

只有零解.

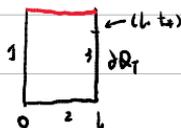
否则在  $\mathbb{R}_T$  上有非零解, 其有正的最大值或负的最小值.

$u = 0$ . 由极值原理, 最大值最小值均在边界处取到

不妨设正的最大值在边界取到

$u(0, t) = u(x, 0) = 0 \Rightarrow$  正的最大值在  $\partial\mathbb{R}_T$  取到

设  $u$  在  $(l, t_*)$  取到正的最大值



$u_x(l, t_*) > 0$ , 故  $u_x + hu(l, t_*) > 0$  与边界条件矛盾

进而给出了第三类边值问题的唯一性

第二类边值问题

$$\begin{cases} u_t - u_{xx} = f(x, t) \\ u(0, t) = \mu_1(t), \quad u_x(l, t) = \mu_2(t) \\ u(x, 0) = \varphi(x) \end{cases}$$

只需证明  $\begin{cases} u_t - u_{xx} = 0 \\ u(0, t) = 0 \quad u_x(l, t) = 0 \\ u(x, 0) = 0 \end{cases}$

只有零解.

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pr: idea  $(uw)_x = u_x w + u w_x$

将第二类边值化为第三类边值

$$\text{令 } \tilde{u}(x, t) = w(x) u(x, t), \quad u = \frac{\tilde{u}}{w}$$

$$\text{则 } u_t = \frac{\tilde{u}_t}{w}, \quad u_x = \frac{\tilde{u}_x w - w_x \tilde{u}}{w^2}, \quad u_{xx} = \left(-\frac{w_{xx}}{w^2} + 2\frac{w_x^2}{w^3}\right) \tilde{u} - 2\frac{w_x}{w^2} \tilde{u}_x + \frac{1}{w} \tilde{u}_{xx}$$

$$\Rightarrow \frac{\tilde{u}_t}{w} + \left(\frac{w_{xx}}{w^2} - 2\frac{w_x^2}{w^3}\right) \tilde{u} + \frac{2w_x}{w^2} \tilde{u}_x - \frac{1}{w} \tilde{u}_{xx}$$

$$\Rightarrow \tilde{u}_t - \tilde{u}_{xx} = -2\frac{w_x}{w} \tilde{u}_x - \left(\frac{w_{xx}}{w} - 2\frac{w_x^2}{w^2}\right) \tilde{u}$$

$$\begin{cases} \tilde{u}(0, t) = 0, & \tilde{u}_x(l, t) = w_x u + u_x w(l, t) = w_x(l) u(l, t) = w_x(l) \cdot \frac{\tilde{u}(l, t)}{w(l)} \\ \tilde{u}(x, 0) = 0 \end{cases}$$

$$\text{hope } \frac{w_x(l)}{w(l)} = -1, \quad \text{取 } w(x) = -x + l + 1$$

$$\text{则 } \begin{cases} \tilde{u}_t - \tilde{u}_{xx} = \frac{2}{-x+l+1} \tilde{u}_x + 2\frac{1}{(-x+l+1)^2} \tilde{u} \quad (*) \\ \tilde{u}(0, t) = 0, \quad (\tilde{u}_x + \tilde{u})(l, t) = 0 \\ \tilde{u}(x, 0) = 0 \end{cases}$$

$$\text{令 } v(x, t) = e^{-\lambda t} \tilde{u}(x, t), \quad \tilde{u} = e^{\lambda t} v$$

$$\tilde{u}_t = v_t e^{\lambda t} + \lambda e^{\lambda t} v$$

$$\tilde{u}_x = e^{\lambda t} v_x \quad \tilde{u}_{xx} = e^{\lambda t} v_{xx}$$

$$\text{则 } \begin{cases} v_t - v_{xx} - \frac{2}{-x+l+1} v_x + \left(\lambda - \frac{2}{(-x+l+1)^2}\right) v = 0 \\ v(0, t) = 0, \quad (v_x + v)(l, t) = 0 \\ v(x, 0) = 0 \end{cases}$$

$$\text{取 } \lambda > 2, \text{ 则 } \lambda - \frac{2}{(-x+l+1)^2} > 0$$

claim:  $v$  在  $\mathbb{Q}_T$  上非负的最大值在边界取到

事实上, 若在  $v(x_0, t_0) = M > 0, (x_0, t_0) \in \mathbb{Q}_T$

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则  $V_t(x_0, t_0) \geq 0$ ,  $V_x(x_0, t_0) = 0$ ,  $V_{xx}(x_0, t_0) \leq 0$

与方程条件矛盾

再利用第三类问题的处理给出第二类问题解的唯一性

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### §3.3 初值问题的最大模估计

实值函数的初值问题

$$\begin{cases} u_t - u_{xx} = f(x, t) & x \in \mathbb{R}, 0 < t \leq T \\ u(x, 0) = \varphi(x) & x \in \mathbb{R} \end{cases}$$

#### thm 1. 最大模估计

假设  $u \in C^{2,1}(\mathbb{Q}_T) \cap C(\bar{\mathbb{Q}}_T)$  为上述问题的有界解

$$\text{则 } \sup_{\mathbb{Q}_T} |u(x, t)| \leq T \sup_{\mathbb{Q}_T} |f(x, t)| + \sup_{x \in \mathbb{R}} |\varphi(x)|$$

$$\text{令 } F = \sup_{\mathbb{Q}_T} |f(x, t)|, \quad \Phi = \sup_{x \in \mathbb{R}} |\varphi(x)|, \quad M = \sup_{\mathbb{Q}_T} |u(x, t)|$$

pr:  $\forall \varepsilon > 0$ , 在  $\mathbb{Q}_T^\varepsilon = (-\varepsilon, \varepsilon) \times (0, T]$  上构造辅助函数

$$w(x, t) = Ft + \Phi + V_\varepsilon(x, t) \pm u(x, t)$$

$$V_\varepsilon(x, t) = \frac{M}{\varepsilon^2} (x^2 + 2t)$$

(idea:  $V_\varepsilon(x, t)$  为自由方程  $V_t - V_{xx} = 0$  的解)

$$\text{则 } w_t - w_{xx} = F \pm f \geq 0$$

由极值原理, 最小值在边界处取到

$$w|_{t=0} = \Phi + \frac{M}{\varepsilon^2} x^2 \pm \varphi(x) \geq 0$$

$$w|_{x=\pm\varepsilon} = F\varepsilon + \Phi + M \pm u \geq 0$$

$$\Rightarrow w(x, t) \geq 0 \quad (x, t) \in \mathbb{Q}_T^\varepsilon$$

$\forall (x_0, t_0) \in \mathbb{Q}_T$ , 取  $\varepsilon$  充分大, st.  $(x_0, t_0) \in \mathbb{Q}_T^\varepsilon$

由于  $w(x_0, t_0) \geq 0$ , 故

$$|u(x_0, t_0)| \leq F t_0 + \Phi + \frac{M}{\varepsilon^2} (x_0^2 + 2t_0)$$

$$\leq FT + \Phi + \frac{M}{\varepsilon^2} (x_0^2 + 2t_0)$$

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令  $L \rightarrow +\infty$ . 则  $|u(x_0, t_0)| \leq FT + \Phi$

由  $(x_0, t_0)$  的任意性,  $\sup_{Q_T} |u(x, t)| \leq T \sup_{Q_T} |f(x, t)| + \sup_{x \in \mathbb{R}} |\varphi(x)|$

Prk. 有界性可以定义为  $|u(x, t)| \leq M e^{Ax^2}$ ,  $(x, t) \in Q_T$

下面用能量估计证明解的唯一性

考虑方程

$$\begin{cases} u_t - u_{xx} = f & (x, t) \in Q_T = (0, l) \times (0, T] \\ u|_{t=0} = \varphi(x) \\ u|_{x=0} = u|_{x=l} = 0 \end{cases}$$

thm 2. 能量不等式

设  $u \in C^{1,0}(\bar{Q}_T) \cap C^{2,1}(Q_T)$  为上述问题的解,

$$\begin{aligned} \text{则 } \sup_{0 \leq t \leq T} \int_0^l u^2(x, t) dx + \int_0^T \int_0^l u_x^2(x, t) dx dt \\ \leq M \left( \int_0^l \varphi^2(x) dx + \int_0^T \int_0^l f^2(x, t) dx dt \right) \end{aligned}$$

$$\text{pr: } (u_t - u_{xx})u = fu$$

$$\text{左: } \frac{1}{2}(u^2)_t - (u u_x)_x + (u_x)^2 = fu$$

在  $[0, l]$  上积分, 有

$$\frac{d}{dt} \frac{1}{2} \int_0^l u^2 dx - u u_x \Big|_{x=0}^{x=l} + \int_0^l u_x^2 dx = \int_0^l fu dx$$

$$\Rightarrow \frac{d}{dt} \left( \frac{1}{2} \int_0^l u^2 dx \right) + \int_0^l u_x^2 dx \leq \frac{1}{2} \int_0^l f^2 dx + \frac{1}{2} \int_0^l u^2 dx$$

$$\Rightarrow \frac{d}{dt} \left( \int_0^l u^2 dx \right) \leq \int_0^l f^2 dx + \int_0^l u^2 dx$$

$$\frac{d}{dt} \left( e^{-t} \int_0^l u^2 dx \right) \leq e^{-t} \int_0^l f^2 dx$$

$$\text{从 } (0, t) \text{ 积分 } \Rightarrow e^{-t} \int_0^l u^2 dx - y(0) \leq \int_0^t e^{-s} \int_0^l f^2(x, s) dx ds$$

$$\text{def } y(t) = \int_0^l u^2(x, t) dx$$

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$$\text{则 } y(t) \leq e^t y(0) + e^t \int_0^t \int_0^l f^2(x,s) dx ds$$

$$\Rightarrow \int_0^l u^2 dx \leq e^t \left( \int_0^l \varphi^2 dx + \int_0^t \int_0^l f^2(x,s) dx ds \right)$$

$$\leq e^T \left( \int_0^l \varphi^2 dx + \int_0^T \int_0^l f^2(x,s) dx ds \right) \quad \forall 0 < t \leq T$$

$$\text{故 } \frac{d}{dt} \left( \frac{1}{2} \int_0^l u^2 dx \right) + \int_0^l u_x^2 dx \leq \frac{1}{2} \int_0^l f^2 dx + \frac{1}{2} e^t \left( \int_0^l \varphi^2 dx + \int_0^T \int_0^l f^2(x,s) dx ds \right)$$

再从 0 到 t 积分, 有

$$\frac{1}{2} \int_0^l u^2 dx + \int_0^t \int_0^l u_x^2 dx dt \leq \frac{1}{2} \int_0^l \varphi^2 dx + \frac{1}{2} \int_0^t \int_0^l f^2 dx dt$$

$$+ \frac{1}{2} (e^t - 1) \left[ \int_0^l \varphi^2 dx + \int_0^T \int_0^l f^2(x,s) dx ds \right]$$

$$\leq \frac{1}{2} e^T \int_0^T \int_0^l f^2(x,s) dx ds \quad \forall 0 < t \leq T$$

$$\Rightarrow \sup_{0 \leq t \leq T} \int_0^l u^2(x,t) dx \geq \int_0^T \int_0^l u_x^2(x,t) dx dt$$

$$\leq e^T \left( \int_0^l \varphi^2(x) dx + \int_0^T \int_0^l f^2(x,t) dx dt \right)$$

Rmk. 可得到解的唯一性与稳定性.

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## 第四章 波动方程

方程的来源: 均匀细弦/薄膜/弹性体的自由/受迫振动

$u(x, t)$  未知  $\Delta u = \frac{\partial^2 u}{\partial x_1^2} + \dots + \frac{\partial^2 u}{\partial x_n^2}$

$$\begin{cases} \frac{\partial^2 u}{\partial t^2} - \Delta u = f(x, t) & x \in \Omega, t > 0 \\ u(x, 0) = f(x) & x \in \Omega \\ u_t(x, 0) = g(x) & x \in \Omega \end{cases} \left. \begin{array}{l} \\ \\ \end{array} \right\} \text{初值, 为关于 } x \text{ 的函数}$$

边值

Rmk. 物理意义

$f(x, t)$  表示单位质量所受外力

第一类边值 (Dirichlet)  $u(x, t) = h(x, t) \quad \forall x \in \partial\Omega$

第二类边值 (Neumann)  $\frac{\partial u}{\partial n}(x, t) = h(x, t) \quad \forall x \in \partial\Omega$

第三类边值 (Robin)  $\frac{\partial u}{\partial n}(x, t) + \alpha(x, t) u(x, t) = h(x, t) \quad \forall x \in \partial\Omega \quad \alpha(x, t) > 0$

Rmk. 边界意义

(Dirichlet) 边界点位移变化

若  $h(x, t) = h(x)$ , 则边界点固定

(Neumann) 边界点受力情况

若  $h(x, t) \equiv 0$ , 则无外力通过边界对弹性体作用

(Robin) 位移与受力线性组合

若  $h(x, t) \equiv 0$ , 则边界固定或支撑

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## §4.1 初值问题

### §4.1.1 一阶偏微分方程的解

$$\text{考虑: } \begin{cases} \frac{\partial u}{\partial t} + a(x,t) \frac{\partial u}{\partial x} + b(x,t)u = f(x,t) \\ u(x,0) = \phi(x) \end{cases}$$

$u(x,t)$  为未知函数  $-\infty < x < +\infty, t > 0$

若  $x = x(t)$ , 令  $u(x(t), t) = U(t)$

$$\frac{dU}{dt} = \frac{\partial u}{\partial t} + \frac{\partial u}{\partial x} x'(t)$$

$x(t)$  称为特征线

$$\text{若 } x'(t) = a(x(t), t), \quad \frac{dU}{dt} + b(x(t), t)U(t) = f(x(t), t)$$

令  $x(0) = c$ , 则  $U(0) = u(x(0), 0) = \phi(c)$

$$\Rightarrow \begin{cases} \frac{dx}{dt} = a(x(t), t) \\ x(0) = c \end{cases} \quad \begin{cases} \frac{dU}{dt} + b(x(t), t)U(t) = f(x(t), t) \\ U(0) = \phi(c) \end{cases}$$

特征线为 2 个 ode

$$\text{ex. } \begin{cases} \frac{dx}{dt} - a \frac{dx}{dx} = 0 \\ u(x,0) = \phi(x) \end{cases}$$

$$\Rightarrow \begin{cases} \frac{dx}{dt} = -a \\ x(0) = c \end{cases} \Rightarrow x(t) = -at + c$$

$$\begin{cases} \frac{dU}{dt} = 0 \\ U(0) = \phi(c) \end{cases} \Rightarrow U = \phi(c)$$

$$U(t) = \phi(x(t) + at) = u(x(t), t)$$

$$\text{取 } u(x, t) = \phi(x + at)$$

$$\text{ex. } \begin{cases} \frac{dx}{dt} - a \frac{dx}{dx} = f(x, t) \\ u(x,0) = \phi(x) \end{cases}$$

$$\Rightarrow \begin{cases} \frac{dx}{dt} = -a \\ x(0) = c \end{cases} \Rightarrow x(t) = -at + c$$

$$\begin{cases} \frac{dU}{dt} = f(x(t), t) \\ U(0) = \phi(c) \end{cases}$$

$$x(t) \text{ 代入, } \frac{dU}{dt} = f(-at + c, t)$$

$$\Rightarrow U(t) = \phi(c) + \int_0^t f(-a\tau + c, \tau) d\tau$$

$$u(x, t) = \phi(x + at) + \int_0^t f(x + a(t-\tau), \tau) d\tau$$

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$$\text{ex. } \begin{cases} \frac{\partial u}{\partial t} + (x+t) \frac{\partial u}{\partial x} + u = x \\ u|_{t=0} = x \end{cases}$$

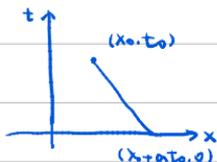
$$\begin{cases} \frac{dx}{dt} = x+t \quad (-\text{阶线性}) \\ x(0) = C \end{cases} \Rightarrow x(t) = Ce^t - t - 1$$

$$\begin{cases} \frac{du}{dt} + U(t) = Ce^t + e^t - t - 1 \\ U(0) = C \end{cases} \Rightarrow U(t) = -t + \frac{1}{2}(e^t - e^{-t}) + \frac{C}{2}(e^t - e^{-t})$$

$$\Rightarrow u(x, t) = \frac{1}{2}(x-t+1) - e^{-t} + \frac{1}{2}(x+t+1)e^{-2t}$$

Rank. 对第一个方程有如下较为几何的解释

在  $x(t) = -at + C$  上, 有  $\frac{du}{dt} = 0$



依据初值  $u(x_0 + at_0, 0) = \phi(x_0 + at_0) = u(x_0, t_0) \quad \forall x_0, t_0$

$$\Rightarrow u(x, t) = \phi(x+at)$$

同样地, 对第二个方程

$$u(x_0 + at_0, 0) = \phi(x_0 + at_0)$$

$$u(x_0, t_0) = u(x_0 + at_0, 0) + \int_0^{t_0} f(x(t), t) dt$$

$$= \phi(x_0 + at_0) + \int_0^{t_0} f(x_0 + a(t_0 - \tau), \tau) d\tau \quad \forall x_0, t_0$$

$$\Rightarrow u(x, t) = \phi(x+at) + \int_0^t f(x+at-\tau, \tau) d\tau$$

特征线法将 PDE 化为 ODE, 最终结果即在特征线上对时间积分



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Rmk. 初值为先给出函数, 如  $\Delta u$ ,  $u_t$ ,  $u_{tt}$ . 再赋值

在上述过程中  $v(x, 0) = \hat{u}_t(x, 0) = \frac{\partial}{\partial t} \hat{u}(x, 0) \times \frac{\partial}{\partial t} 0 = 0$

对其余变量求偏导时, 可交换给出函数与赋值顺序

$$\text{令 } \hat{u}_1(x, t) = M_{f_t}(x, t), \text{ 则 } \begin{cases} \partial_t^2 \hat{u}_1 - \Delta \hat{u}_1 = 0 \\ \hat{u}_1(x, 0) = 0 \\ \partial_t \hat{u}_1(x, 0) = f_t = f(x, T) \quad T \text{ 为参数} \end{cases}$$

令  $v(x, t) = M_{f_t}(x, t-T) = \hat{u}_1(x, t-T)$ , 则

$$\begin{cases} \partial_t^2 v - \Delta v = (\partial_t^2 \hat{u}_1 - \Delta \hat{u}_1)(x, t-T) = 0 \\ v|_{t=T} = \hat{u}_1(x, 0) = 0 \\ \partial_t v|_{t=T} = \partial_t \hat{u}_1(x, 0) = f(x, T) \end{cases}$$

$$u_3 = \int_0^t M_{f_t}(x, t-\tau) d\tau$$

$$\begin{aligned} \partial_t u_3 &= M_{f_t}(x, 0) + \int_0^t \frac{\partial}{\partial t} M_{f_t}(x, t-\tau) d\tau \\ &= \int_0^t \frac{\partial}{\partial t} M_{f_t}(x, t-\tau) d\tau \end{aligned}$$

$$\begin{aligned} \partial_t^2 u_3 &= \frac{\partial}{\partial t} M_{f_t}(x, 0) + \int_0^t \frac{\partial^2}{\partial t^2} M_{f_t}(x, t-\tau) d\tau \\ &= f(x, t) + \int_0^t \Delta M_{f_t}(x, t-\tau) d\tau \\ &= f(x, t) + \Delta \int_0^t M_{f_t}(x, t-\tau) d\tau \\ &= f(x, t) + \Delta u_3 \end{aligned}$$

$$\text{且 } u_3(x, 0) = 0, \partial_t u_3(x, 0) = 0$$

Rmk. " $\Delta$ "可写出来, 由于为对  $x$  的导数, 积分限不含  $x$

该过程被称作冲量原理 (Duhamel) 非齐次右端  $\rightarrow$  具有初速度齐次右端的和

$$u_3(x, t) = \lim_{\|z\| \rightarrow 0} \sum_{i=0}^{n-1} M_{f_t}(x, t-t_i) \Delta t_i = \lim_{\|z\| \rightarrow 0} \sum_{i=0}^{n-1} M_{f_t}(x, t-t_i)$$

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$$\text{该问题转化为如何考查方程 } \begin{cases} \partial_t^2 u - \Delta u = 0 \\ u(x, 0) = 0, \partial_t u(x, 0) = \psi(x) \end{cases}$$

的解, thm 1. 指出了“速度”方程具有平反性.

Recall: 傅立叶变换  $\hat{f}(\xi) = \int_{\mathbb{R}^n} f(x) e^{-2\pi i x \cdot \xi} dx$   $\xi$  为参向量

$$\begin{aligned} \Delta \hat{f}(\xi) &= \int_{\mathbb{R}^n} \Delta f(x) e^{-2\pi i x \cdot \xi} dx = \sum_j \int_{\mathbb{R}^n} f_{x_j x_j} e^{-2\pi i x \cdot \xi} dx \\ &= - \sum_j \int_{\mathbb{R}^n} f_{x_j} \cdot (-2\pi i \xi_j) e^{-2\pi i x \cdot \xi} dx \end{aligned}$$

$f, f_{x_j}$  在无穷远处  $\rightarrow 0$

$$\begin{aligned} &= - \sum_j (-2\pi i \xi_j) \int_{\mathbb{R}^n} f_{x_j} e^{-2\pi i x \cdot \xi} dx \\ &= \sum_j (-2\pi i \xi_j)^2 \int_{\mathbb{R}^n} f e^{-2\pi i x \cdot \xi} dx \\ &= -4\pi^2 |\xi|^2 \hat{f}(\xi) \end{aligned}$$

将分析运算转化为代数运算

$$\text{方程 } \begin{cases} \partial_t^2 u - \Delta u = 0 \\ u|_{t=0} = \varphi(x), u_t|_{t=0} = \psi(x) \end{cases}$$

$$\text{两边关于 } x \text{ 的傅立叶变换, } \begin{cases} \partial_t^2 \hat{u}(\xi, t) + 4\pi^2 |\xi|^2 \hat{u}(\xi, t) = 0 \\ \hat{u}(\xi, 0) = \hat{\varphi}(\xi), \partial_t \hat{u}(\xi, 0) = \hat{\psi}(\xi) \end{cases}$$

$\xi$  视为参数, 则为二阶常微分方程,  $\lambda^2 + 4\pi^2 |\xi|^2 = 0 \Rightarrow \lambda = \pm 2\pi |\xi| i$

$$\Rightarrow \hat{u}(\xi, t) = C_1 \cos(2\pi t |\xi|) + C_2 \sin(2\pi t |\xi|)$$

$$\hat{u}(\xi, 0) = C_1 = \hat{\varphi}(\xi)$$

$$\partial_t \hat{u}(\xi, 0) = C_2 \cdot 2\pi |\xi| = \hat{\psi}(\xi)$$

$$\Rightarrow \hat{u}(\xi, t) = \cos(2\pi t |\xi|) \hat{\varphi}(\xi) + \frac{\sin(2\pi t |\xi|)}{2\pi |\xi|} \hat{\psi}(\xi)$$

Rmk. 也说明了  $u_1, u_2$  解的关系

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$$\text{方程 } \begin{cases} \partial_t^2 u_3 - \Delta u_3 = f(x, t) \\ u_3(x, 0) = 0, \partial_t u_3(x, 0) = 0 \end{cases}$$

$$\text{关于 } x \text{ 做傅立叶变换, } \begin{cases} \partial_t^2 \hat{u}_3 + 4z^2 |\xi|^2 \hat{u}_3 = f(\xi, t) \\ \hat{u}_3(\xi, 0) = 0, \partial_t \hat{u}_3(\xi, 0) = 0 \end{cases}$$

$$\Rightarrow \hat{u}_3(\xi, t) = \int_0^t \frac{\sin(2|\xi|(t-\tau))}{2|\xi|} f(\xi, \tau) d\tau$$

rmk. 也说明了  $u_2, u_3$  的关系.

若对  $x, t$  同时变换  $x \rightarrow \xi, t \rightarrow s$

$$-4z^2 s^2 \hat{u} + 4z^2 |\eta|^2 \hat{u} = 0$$

$$\Rightarrow (|\eta|^2 - s^2) \hat{u}(s, \xi) = 0$$

$$\Rightarrow s^2 = |\eta|^2 \quad (s, \eta) \in \mathbb{R}^{1+n} \text{ 构成锥面}$$

表明  $\hat{u}$  仅在锥面上可不为 0. 设方程对时空的 Fourier 变换  
支在锥面上.

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### § 4.1.3 一维初值问题

$$\text{在 } \mathbb{R} \text{ 上波动方程 } \begin{cases} \partial_t^2 u - \partial_x^2 u = f(x, t) & x \in \mathbb{R}, t > 0 \\ u(x, 0) = \varphi(x) & x \in \mathbb{R} \\ \partial_t u(x, 0) = \Psi(x) & x \in \mathbb{R} \end{cases} \quad (4.13)$$

Remark.  $x$  的范围会影响解方程的方法与结果

$$\begin{cases} \partial_t^2 u_2 - \Delta u_2 = 0 \\ u_2(x, 0) = 0 \\ \partial_t u_2(x, 0) = \Psi(x) \end{cases} \quad (4.8) \quad \text{(由上节 thm 知只需求解该方程即得一维波动方程的解)}$$

$$\text{即 } (\partial_t + \partial_x)(\partial_t - \partial_x)u = 0$$

$$\text{令 } v(x, t) = (\partial_t - \partial_x)u, \text{ 则 } \begin{cases} \partial_t v + \partial_x v = 0 \\ v(x, 0) = (\partial_t - \partial_x)u(x, 0) = \Psi(x) \end{cases}$$

$$\Rightarrow v(x, t) = \Psi(x-t)$$

$$\begin{cases} \partial_t u - \partial_x u = \Psi(x-t) \\ u(x, 0) = 0 \end{cases}$$

$$\Rightarrow u(x, t) = \int_0^t \underbrace{\Psi(x+t-2\tau)}_{\substack{\parallel \Delta \\ y}} d\tau$$

$$= \frac{1}{2} \int_{x-t}^{x+t} \Psi(y) dy$$

$$\text{故 } u_2(x, t) = \frac{1}{2} \int_{x-t}^{x+t} \Psi(y) dy$$

$$u_1(x, t) = \frac{1}{2} \int_{x-t}^{x+t} \varphi(y) dy$$

$$= \frac{1}{2} (\varphi(x+t) + \varphi(x-t))$$

故 (4.13) 解为

$$u_1 + u_2 + u_3 \quad (4.20)$$

thm 2 (D'Alembert 公式)

$$u_3(x, t) = \int_0^t \frac{1}{2} \int_{x-t-\tau}^{x+t-\tau} f(y, \tau) dy d\tau$$

$$= \frac{1}{2} \int_0^t \int_{x-t-\tau}^{x+t-\tau} f(y, \tau) dy d\tau$$

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$$\text{若 } f \equiv 0, \text{ 令 } F(x) = \frac{1}{2}\varphi(x) + \frac{1}{2}\int_0^x \psi(y) dy$$

$$G(x) = \frac{1}{2}\varphi(x) + \frac{1}{2}\int_x^0 \psi(y) dy$$

$$\Rightarrow u(x, t) = F(x+t) + G(x-t)$$

右行波      右行波

thm 3    给出形式解存在条件 (形式解  $\rightarrow$  古典解)

$$\varphi \in C^2(\mathbb{R}), \psi \in C^1(\mathbb{R}), f \in C^1(\mathbb{R} \times \mathbb{R}^+)$$

则 (4.20) 给出的函数  $u \in C^2(\mathbb{R} \times \mathbb{R}^+)$ , 且为初值问题 (4.13) 解

$$\text{pr. } u(x, t) = \frac{1}{2}(\varphi(x+at) + \varphi(x-at)) + \frac{1}{2a} \int_{x-at}^{x+at} \psi(y) dy + \frac{1}{2a} \int_0^t \int_{x-at-\tau}^{x+at-\tau} f(y, \tau) dy d\tau$$

①  $u(x, t) \in C(\mathbb{R} \times \mathbb{R}^+)$  为连续函数 复合 / 变限积分

$$\begin{aligned} \text{② } u_t(x, t) &= \frac{a}{2}\varphi'(x+at) - \frac{a}{2}\varphi'(x-at) + \frac{1}{2a} (a\psi(x+at) + a\psi(x-at)) \\ &\quad + \frac{1}{2a} \int_0^t a f(x+at-\tau, \tau) + a f(x-at-\tau, \tau) d\tau \end{aligned}$$

$$\begin{aligned} u_x(x, t) &= \frac{1}{2}\varphi'(x+at) + \frac{1}{2}\varphi'(x-at) + \frac{1}{2a} (\psi(x+at) - \psi(x-at)) \\ &\quad + \frac{1}{2a} \int_0^t f(x+at-\tau, \tau) - f(x-at-\tau, \tau) d\tau \end{aligned}$$

$u(x, t) \in C^1(\mathbb{R} \times \mathbb{R}^+)$ , 由于  $u_t, u_x \in C(\mathbb{R} \times \mathbb{R}^+)$

$$\begin{aligned} \text{③ } u_{tt}(x, t) &= \frac{a^2}{2}\varphi''(x+at) + \frac{a^2}{2}\varphi''(x-at) + \frac{1}{2a} (a^2\psi'(x+at) - a^2\psi'(x-at)) \\ &\quad + \frac{1}{2a} [2af_x(x, t) + \int_0^t a^2 f_{xx}(x+at-\tau, \tau) - a^2 f_{xx}(x-at-\tau, \tau) d\tau] \end{aligned}$$

$$\begin{aligned} u_{xx}(x, t) &= \frac{1}{2}\varphi''(x+at) + \frac{1}{2}\varphi''(x-at) + \frac{1}{2a} (\psi'(x+at) - \psi'(x-at)) \\ &\quad + \frac{1}{2a} \int_0^t [f_{xx}(x+at-\tau, \tau) - f_{xx}(x-at-\tau, \tau)] d\tau \end{aligned}$$

$$\begin{aligned} u_{xt}(x, t) &= \frac{a}{2}\varphi''(x-at) - \frac{a}{2}\varphi''(x+at) + \frac{1}{2} (\psi'(x+at) + \psi'(x-at)) \\ &\quad + \frac{1}{2a} \int_0^t a f_{xx}(x+at-\tau, \tau) + a f_{xx}(x-at-\tau, \tau) d\tau \end{aligned}$$

$$\in C(\mathbb{R} \times \mathbb{R}^+) = u_{tx}(x, t)$$

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$$u(x, t) \in C^2(\mathbb{R} \times \mathbb{R}_+)$$

$$\textcircled{+} u_{tt} - a^2 u_{xx} = f(x, t)$$

$$u(x, 0) = \varphi(x), \quad u_t(x, 0) = \psi(x)$$

则  $u$  为初值问题的解

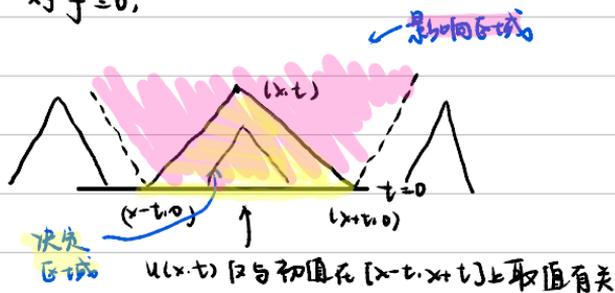
#### thm 4 利用形式解分析性质

若  $\varphi, \psi, f$  为  $x$  的偶/奇/周期为  $l$  函数

由 (4.20) 给出的解  $u$  为  $x$  的偶/奇/周期为  $l$  函数

Remark. 几何性质

对  $f \equiv 0$ ,



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### § 4.1.4 一维半无界问题

$$\text{考虑波动方程} \begin{cases} \partial_t^2 u - \partial_x^2 u = f(x, t) & x > 0, t > 0 \\ u(x, 0) = \varphi(x) & x \geq 0 \quad (4.21) \\ \partial_t u(x, 0) = \psi(x) & x \geq 0 \\ u(0, t) = g(t) & t \geq 0 \quad (\text{边界}) \end{cases}$$

1. 若  $g(t) \equiv 0$ , 作奇延拓.

$$\text{令 } \bar{\varphi}(x) = \begin{cases} \varphi(x) & x \geq 0 \\ -\varphi(-x) & x < 0 \end{cases} \quad \bar{\psi}(x) = \begin{cases} \psi(x) & x \geq 0 \\ -\psi(-x) & x < 0 \end{cases} \quad \bar{f}(x, t) = \begin{cases} f(x, t) & x \geq 0 \\ -f(-x, t) & x < 0 \end{cases}$$

Rmk. 奇延拓, 则  $w(0) = 0$ ; 偶延拓, 则  $w'(0) = 0$

$$\text{令 } \bar{u}(x, t) \text{ 为方程 } \begin{cases} \partial_t^2 \bar{u} - \partial_x^2 \bar{u} = \bar{f}(x, t) & x \in \mathbb{R}, t > 0 \\ \bar{u}(x, 0) = \bar{\varphi}(x) & x \in \mathbb{R} \\ \partial_t \bar{u}(x, 0) = \bar{\psi}(x) & x \in \mathbb{R} \end{cases}$$

的解, 由于对  $x$  的奇性,  $\bar{u}(0, t) = 0, t \geq 0$  满足边界

$$\text{由 (4.20), } \bar{u}(x, t) = \frac{1}{2}(\bar{\varphi}(x+t) + \bar{\varphi}(x-t)) + \frac{1}{2} \int_{x-t}^{x+t} \bar{\psi}(y) dy + \frac{1}{2} \int_0^t \int_{x-(t-\tau)}^{x+(t-\tau)} \bar{f}(y, \tau) dy d\tau$$

$x > 0, x \geq t$  时.

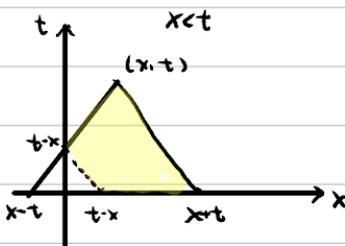
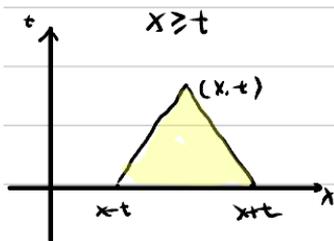
$x \in \mathbb{R}, t > 0$

$$u(x, t) = \frac{1}{2}(\varphi(x+t) + \varphi(x-t)) + \frac{1}{2} \int_{x-t}^{x+t} \psi(y) dy + \frac{1}{2} \int_0^t \int_{x-(t-\tau)}^{x+(t-\tau)} f(y, \tau) dy d\tau \quad (4.23)$$

$x > 0, x < t$  时.

$$\begin{aligned} u(x, t) &= \frac{1}{2}(\varphi(x+t) - \varphi(t-x)) + \frac{1}{2} \int_0^{x+t} \psi(y) dy + \frac{1}{2} \int_{x-t}^0 -\psi(-y) dy \\ &+ \frac{1}{2} \int_{t-x}^t \int_{x-(t-\tau)}^{x+(t-\tau)} f(y, \tau) dy d\tau + \frac{1}{2} \int_0^{t-x} \int_0^{x+(t-\tau)} f(y, \tau) dy d\tau + \frac{1}{2} \int_0^{t-x} \int_{x-(t-\tau)}^0 -f(-y, \tau) dy d\tau \\ &= \frac{1}{2}(\varphi(x+t) - \varphi(t-x)) + \frac{1}{2} \int_{t-x}^{t+x} \psi(y) dy \\ &+ \frac{1}{2} \int_{t-x}^t \int_{x-(t-\tau)}^{x+(t-\tau)} f(y, \tau) dy d\tau + \frac{1}{2} \int_0^{t-x} \int_{(t-\tau)-x}^{(t-\tau)+x} f(y, \tau) dy d\tau \quad (4.24) \end{aligned}$$

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黄色部分所示为积分区域

如何完成从形式解到古典解过渡? Rmk. 古典解: 所需的所有阶偏导数连续可积.

且在边界处连续

相容性条件:

$$\begin{aligned} \textcircled{1} \quad \lim_{x \rightarrow 0^+} u(x, 0) &= u(0, 0) = \lim_{t \rightarrow 0^+} u(0, t) \\ &\parallel \qquad \qquad \parallel \\ \varphi(0) & \qquad \qquad g(0) = 0 \qquad \varphi(0) = 0 \quad (4.25) \end{aligned}$$

$$\begin{aligned} \textcircled{2} \quad \lim_{x \rightarrow 0^+} u_x(x, 0) &= u_x(0, 0) = \lim_{t \rightarrow 0^+} u_x(0, t) \\ &\parallel \qquad \qquad \parallel \\ \psi(0) & \qquad \qquad g'(0) = 0 \qquad \psi(0) = 0 \quad (4.26) \end{aligned}$$

$$\begin{aligned} \textcircled{3} \quad \lim_{x \rightarrow 0^+} u_{xx}(x, 0) &= u_{xx}(0, 0) = \lim_{t \rightarrow 0^+} u_{xx}(0, t) \\ &\parallel \qquad \qquad \parallel \\ \lim_{x \rightarrow 0^+} (\partial_x^2 u(x, 0) + f(x, 0)) & \qquad \qquad g''(0) = 0 \qquad \varphi''(0) + f(0, 0) = 0 \quad (4.27) \\ &\parallel \qquad \qquad \parallel \\ \varphi''(0) + f(0, 0) & \end{aligned}$$

### thm 5

若 (4.21) 初值  $\varphi(x) \in C^2(\bar{R}^+)$ ,  $\psi(x) \in C^1(\bar{R}^+)$ ,  $f(x, t) \in C^1(\bar{R}^+ \times \bar{R}^+)$

满足相容性条件, 且也值  $g(t) \leq 0$ . (4.23), (4.24) 给出函数  $u \in C^2(\bar{R}^+ \times \bar{R}^+)$

且为 (4.21) 的解

2. 若  $g(t) \neq 0$ , 令  $v(x, t) = u(x, t) - g(t)$

则  $v(0, t) = u(0, t) - g(t) = 0$

原方程转化为

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$$\begin{cases} \partial_t^2 v - \partial_x^2 v = f(x, t) - g''(t) \\ v(x, 0) = u(x, 0) - g(0) = \varphi(x) - g(0) \\ \partial_t v(x, 0) = \partial_t u(x, 0) - g'(0) = \psi(x) - g'(0) \end{cases}$$

即转化为情形1.

再给出更一般相容性条件

thm 6 相容性条件

$$\varphi(0) = g(0), \quad \psi(0) = g'(0), \quad f(0, 0) + \varphi''(0) = g''(0)$$

Rmk. 相容性条件保证了初值与边值无不可做时的自治.

thm 7 第二类边值问题

给定  $u_x(0, t) = g(t)$ . 则令  $u(x, t) = xg(t) + v(x, t)$

$v(x, t)$  满足  $v_x(0, t) = 0$ . 之后利用隔延拓得到  $v(x, t)$ , 进而得到  $u(x, t)$

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### § 4.1.5 三维初值问题

$$n=3 \quad \begin{cases} \partial_t^2 u - \Delta u = f(x, t) \\ u(x, 0) = \varphi(x), \quad u_t(x, 0) = \psi(x) \end{cases}$$

在极坐标系下,  $\Delta u = \partial_r^2 u + \frac{2}{r} \partial_r u + \frac{1}{r^2} \Delta_S u$  ( $\Delta_S$  表示  $S^2$  上 Laplace)

$$\partial_t^2 u - \left( \partial_r^2 u + \frac{2}{r} \partial_r u + \frac{1}{r^2} \Delta_S u \right) = f(x, t) \quad \Delta \equiv \operatorname{div} \nabla$$

1. 先考虑  $f(x, t) = 0$  情形

$$\begin{aligned} \int_{S^2} \Delta_S u \, d\omega &= \int_{S^2} \operatorname{div} \nabla u \, d\omega \\ &= \int_{S^2} \frac{\partial u}{\partial n} \, ds = 0 \end{aligned}$$

$$\partial_t^2 u - \left( \partial_r^2 u + \frac{2}{r} \partial_r u + \frac{1}{r^2} \Delta_S u \right) = 0$$

对方程两边在  $S^2$  上积分,  $S^2$  为单位球面

$$\partial_t^2 \int_{S^2} u \, d\omega - \left( \partial_r^2 \int_{S^2} u \, d\omega + \frac{2}{r} \partial_r \int_{S^2} u \, d\omega \right) = 0$$

$$\text{令 } \bar{u}(t, r) = \frac{1}{4\pi} \int_{S^2} u \, d\omega$$

$$\text{则 } \partial_t^2 \bar{u} - \partial_r^2 \bar{u} - \frac{2}{r} \partial_r \bar{u} = 0$$

$$\text{令 } \bar{u}(t, r) = r^k V(t, r)$$

$$\partial_r \bar{u} = -k r^{k-1} V(t, r) + r^k \partial_r V$$

$$\begin{aligned} \partial_r^2 \bar{u} &= -k [(-k-1)r^{k-2} V(t, r) + r^{k-1} \partial_r V] + (-k)r^{k-1} \partial_r V + r^k \partial_r^2 V \\ &= k(k+1)r^{k-2} V - 2kr^{k-1} \partial_r V + r^k \partial_r^2 V \end{aligned}$$

$$\begin{aligned} \partial_t^2 \bar{u} + \frac{2}{r} \partial_r \bar{u} &= k(k+1)r^{k-2} V - 2kr^{k-1} \partial_r V + r^k \partial_r^2 V \\ &\quad - 2kr^{k-2} V + 2r^{k-1} \partial_r V \end{aligned}$$

$$\text{取 } k=1, \quad V(t, r) = r \bar{u}(t, r)$$

$$\text{有 } \begin{cases} \partial_t^2 V - \partial_r^2 V = 0 \end{cases}$$

$$\begin{cases} V(r, 0) = r \bar{u}(r, 0) = r \bar{\varphi}(r) & r \geq 0, \text{ " " 表示积分} \\ \partial_t V(r, 0) = r \partial_t \bar{u}(r, 0) = r \bar{\psi}(r) \end{cases}$$

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将  $v$  关于  $r$  作偶延拓, 得到  $\bar{v}$

以下由 "-" 代表延拓后函数

$$\Rightarrow \bar{v}(r, t) = \frac{1}{2}((r+t)\bar{\varphi}(r+t) + (r-t)\bar{\varphi}(r-t)) + \frac{1}{2} \int_{r-t}^{r+t} \psi(\eta) d\eta$$

R<sub>0</sub>t<sub>1</sub>

$\partial_t^2 u - \Delta u = 0$  在以下变换中不变:

时间平移:  $u(x, t) \mapsto u(x, t+t_0)$

空间平移:  $u(x, t) \mapsto u(x+x_0, t)$

伸缩变换:  $u(x, t) \mapsto u(\frac{x}{\lambda}, \frac{t}{\lambda}) \quad \lambda > 0 \equiv u^\lambda(x, t)$

$$(\partial_x u^\lambda(x, t) = \partial_x (u(\frac{x}{\lambda}, \frac{t}{\lambda})) = (\partial_x u)(\frac{x}{\lambda}, \frac{t}{\lambda}) \cdot \frac{1}{\lambda}$$

$$\partial_t^2 u^\lambda(x, t) = (\partial_t^2 u)(\frac{x}{\lambda}, \frac{t}{\lambda}) \cdot \frac{1}{\lambda^2}$$

$$\text{故 } \partial_t^2 u^\lambda - \Delta u^\lambda = (\partial_t^2 u)(\frac{x}{\lambda}, \frac{t}{\lambda}) \cdot \frac{1}{\lambda^2} - \frac{1}{\lambda^2} (\Delta u)(\frac{x}{\lambda}, \frac{t}{\lambda}) = 0$$

$$\text{Lorentz 变换: } u(x, t) \mapsto u(x - xv + \frac{xv - vt}{\sqrt{1-v^2}}, \frac{t - v \cdot x}{\sqrt{1-v^2}})$$

$$xv \equiv (x \frac{v}{|v|}) \frac{|v|}{|v|}$$

以上方程中  $\bar{v} \rightarrow v \rightarrow \bar{u}$ ,  $v$  为速度  $\bar{u}$  与  $u$  的关系

$$\bar{u}(r, t) = \frac{1}{4\pi} \int_{S^2} u \, d\omega = \frac{1}{4\pi} \int_{S^2} u(r, \omega) \, d\omega$$

$$\begin{aligned} \bar{u}(0, t) &= u(0, t) = \partial_r (r \bar{u}(r, t)) \Big|_{r=0} \\ &= \partial_r v \Big|_{r=0} \end{aligned}$$

$$= \frac{1}{2} (\bar{\varphi}(t) + t \bar{\varphi}'(t) + \bar{\varphi}(-t) - t \bar{\varphi}'(-t))$$

$$+ \frac{1}{2} (t \bar{\psi}(t) - (-t) \bar{\psi}(-t))$$

$$= \bar{\varphi}(t) + t \bar{\varphi}'(t) + t \bar{\psi}(t)$$

$$= \frac{d}{dt} (t \bar{\varphi}(t) + t \bar{\psi}(t))$$

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$$= \frac{d}{dt} (t\bar{\varphi}(t)) + t\bar{\Psi}(t)$$

$$= \frac{d}{dt} \left( \frac{t}{4\pi} \int_{S^2} \varphi(t\omega) d\omega \right) + \frac{t}{4\pi} \int_{S^2} \Psi(t\omega) d\omega$$

对  $u(x+x_0, t)$  应用于上一式,

其初值为  $\varphi(x+x_0), \Psi(x+x_0)$

令  $x=0$ ,

$$u(x_0, t) = \frac{d}{dt} \left( \frac{t}{4\pi} \int_{S^2} \varphi(x_0 + t\omega) d\omega \right) + \frac{t}{4\pi} \int_{S^2} \Psi(x_0 + t\omega) d\omega$$

$$x_0 \rightarrow x, \quad y = x + t\omega$$

$$u(x, t) = \frac{d}{dt} \left( \frac{1}{4\pi t} \int_{|y-x|=t} \varphi(y) dS(y) + \frac{1}{4\pi t} \int_{|y-x|=t} \Psi(y) dS(y) \right)$$

(Kirchhoff)

2.  $f$  不恒为 0

$$u(x, t) = \frac{d}{dt} \left( \frac{1}{4\pi t} \int_{|y-x|=t} \varphi(y) dS(y) + \frac{1}{4\pi t} \int_{|y-x|=t} \Psi(y) dS(y) \right) + \int_0^t \frac{1}{4\pi(t-\tau)} \int_{|y-x|=t-\tau} f(y, z) dy d\tau$$

Remark: 反问题时可借助转化为-1维波动方程问题

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## § 4.1.6 二维初值问题

$$n=2, \begin{cases} \partial_t^2 u - \Delta u = f(x, t) \\ u(x, 0) = \varphi(x), u_t(x, 0) = \psi(x) \end{cases}$$

1.  $f(x, t) \equiv 0$ 

$$\text{令 } \tilde{u}(\tilde{x}, t) = u(\tilde{x}, t) \quad \tilde{x} = (x_1, x_2, x_3)$$

$$\tilde{\varphi}(\tilde{x}) = \varphi(x_1, x_2)$$

$$\tilde{\psi}(\tilde{x}) = \psi(x_1, x_2)$$

则  $\tilde{u}(\tilde{x}, t)$  为三维波方程的解.

$$\text{即 } \begin{cases} \partial_t^2 \tilde{u} - \Delta \tilde{u} = 0 \\ \tilde{u}(\tilde{x}, 0) = \tilde{\varphi}(\tilde{x}), \partial_t \tilde{u}(\tilde{x}, 0) = \tilde{\psi}(\tilde{x}) \end{cases}$$

由 Kirchhoff,

$$\tilde{u}(\tilde{x}, t) = \frac{d}{dt} \left( \frac{1}{42t} \int_{|\tilde{x}-\tilde{y}|=t} \tilde{\varphi}(\tilde{y}) dS(\tilde{y}) \right) + \frac{1}{42t} \int_{|\tilde{x}-\tilde{y}|=t} \tilde{\psi}(\tilde{y}) dS(\tilde{y})$$

$$\text{即 } u(x, t)$$

$$x_1, x_2, x_3 = 0 \text{ 时, } \hat{u}(0, t) = u(0, t) = \frac{d}{dt} \left( \frac{1}{42t} \int_{|y_1|=t} \varphi(y_1, y_2) dS(\tilde{y}) \right) + \frac{1}{42t} \int_{|y_1|=t} \psi(y_1, y_2) dS(\tilde{y})$$

$$\text{注意到 } \int_{|y_1|=t} \psi(y_1, y_2) dS(\tilde{y})$$

$$= 2 \int_{y_3 = \sqrt{t^2 - y_1^2 - y_2^2}} \psi(y_1, y_2) dS(\tilde{y})$$

$$= 2 \int_{y_1^2 + y_2^2 \leq t^2} \psi(y_1, y_2) \sqrt{1 + \left(\frac{\partial y_3}{\partial y_1}\right)^2 + \left(\frac{\partial y_3}{\partial y_2}\right)^2} dy_1 dy_2$$

$$= 2 \int_{y_1^2 + y_2^2 \leq t^2} \psi(y_1, y_2) \frac{t}{\sqrt{t^2 - y_1^2 - y_2^2}} dy_1 dy_2$$

$$\frac{\partial y_3}{\partial y_1} = \frac{-y_1}{\sqrt{t^2 - y_1^2 - y_2^2}}$$

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$$\Rightarrow u(0, t) = \frac{d}{dt} \left( \frac{1}{2\sqrt{t}} \int_{|0|+t}^{\infty} \frac{\varphi(y, y_0)}{\sqrt{t^2 - y_0^2}} dy_0 dy_2 \right) + \frac{1}{2\sqrt{t}} \int_{|0|+t}^{\infty} \frac{\psi(y, y_0)}{\sqrt{t^2 - y_0^2}} dy_0 dy_2$$

对  $u(x+x_0, t)$  利用倍论

$$u(x, t) = \frac{d}{dt} \left( \frac{1}{2\sqrt{t}} \int_{|x|+t}^{\infty} \frac{\varphi(y+x_0)}{\sqrt{t^2 - y_0^2}} dy_0 \right) + \frac{1}{2\sqrt{t}} \int_{|x|+t}^{\infty} \frac{\psi(y+x_0)}{\sqrt{t^2 - y_0^2}} dy_0$$

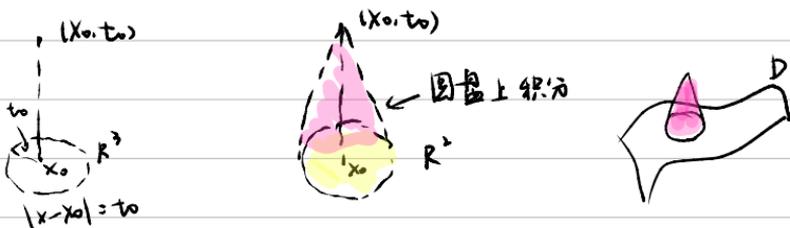
由  $x_0$  任意性  $u(x, t) = \frac{d}{dt} \left( \frac{1}{2\sqrt{t}} \int_{|y-x|+t}^{\infty} \frac{\varphi(y)}{\sqrt{t^2 - (y-x)^2}} dy \right) + \frac{1}{2\sqrt{t}} \int_{|y-x|+t}^{\infty} \frac{\psi(y)}{\sqrt{t^2 - (y-x)^2}} dy$

2.  $f \neq 0$

3. 恒度

$$u(x, t) = \frac{d}{dt} \left( \frac{1}{4\sqrt{t}} \int_{|y-x|+t}^{\infty} \varphi(y) dS(y) + \frac{1}{4\sqrt{t}} \int_{|y-x|+t}^{\infty} \psi(y) dS(y) \right) \quad (\text{Kirchhoff})$$

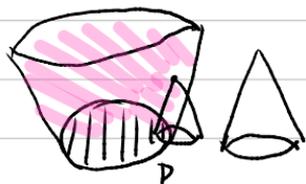
$(x_0, t_0)$  及与初值在球面上积分有关



**依赖区域**:  $(x_0, t_0)$  依赖于  $\{x \mid |x - x_0| \leq t_0\}$  的值  
即  $D_{x_0, t_0}$

**决定区域**:  $\{(x, t) \mid D_{x, t} \subset D\}$  为  $D$  的决定区域

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影响区域

Rmk. 几何恒等

1. 波函数具有有限传播速度

2. Huygens 原理

$n=3$ , 依赖于球面

$n=2$ , 依赖于圆盘内

3.



光锥 因果律

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### §4.1.7 能量估计

$$u_{tt} - \Delta u = 0 \Rightarrow u_t (u_{tt} - \Delta u) = 0$$

$$u_t u_{tt} = \frac{1}{2} \partial_t (u_t)^2$$

$$\begin{aligned}
u_t \Delta u &= \sum_{i=1}^n u_t u_{x_i^2} = \sum_{i=1}^n [\partial x_i (u_t u_{x_i}) - \partial_t \partial x_i u u_{x_i}] \\
&= \sum_{i=1}^n [\partial x_i (u_t u_{x_i}) - \frac{1}{2} \partial_t (u_{x_i})^2] \\
&= \operatorname{div} (u_t \nabla u) - \frac{1}{2} \partial_t |\nabla u|^2
\end{aligned}$$

$$\Rightarrow \partial_t \left[ \frac{1}{2} (u_t)^2 + \frac{1}{2} |\nabla u|^2 \right] - \operatorname{div} (u_t \nabla u) = 0$$

称作能量守恒微分形式

$u, \nabla u$  导数在空间无穷远  $\rightarrow 0$

$$\text{则 } \partial_t \int_{\mathbb{R}^n} \left( \frac{1}{2} u_t^2 + \frac{1}{2} |\nabla u|^2 \right) dx - \int_{\mathbb{R}^n} \operatorname{div} (u_t \nabla u) = 0$$

散度定理  $\int_{\Omega} \operatorname{div} \vec{F} dx = \int_{\partial \Omega} \vec{F} \cdot \vec{n} ds$

$$\Rightarrow \partial_t \int_{\mathbb{R}^n} \left( \frac{1}{2} u_t^2 + \frac{1}{2} |\nabla u|^2 \right) dx = 0$$

令  $E(t) = \int_{\mathbb{R}^n} \frac{1}{2} u_t^2 + \frac{1}{2} |\nabla u|^2 dx$ , 则  $E'(t) = E'(0)$

称作能量守恒积分形式

考虑  $\begin{cases} \partial_t^2 u - \Delta u = 0 & x \in \Omega \subset \mathbb{R}^n, t > 0 \\ u|_{\partial \Omega} = 0, u(x, 0) = \varphi(x), u_t(x, 0) = \psi(x) \end{cases}$

$$\partial_t \left[ \frac{1}{2} (u_t)^2 + \frac{1}{2} |\nabla u|^2 \right] = \operatorname{div} (u_t \nabla u)$$

$$\begin{aligned}
\frac{d}{dt} \int_{\Omega} \left( \frac{1}{2} (u_t)^2 + \frac{1}{2} |\nabla u|^2 \right) dx &= \int_{\Omega} \operatorname{div} (u_t \nabla u) dx \\
&= \int_{\partial \Omega} u_t \nabla u \cdot \vec{n} ds \\
&= \int_{\partial \Omega} u_t \frac{\partial u}{\partial n} ds
\end{aligned}$$

$$u|_{\partial \Omega} = 0 \Rightarrow u_t|_{\partial \Omega} = 0 \Rightarrow E'(t) = \int_{\Omega} \frac{1}{2} u_t^2 + \frac{1}{2} |\nabla u|^2, \text{ 有 } E(t) = E(0)$$

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$$\text{考虑 } \begin{cases} \Delta_t^2 u - \Delta u = f(x, t) & x \in \Omega, t > 0 \\ u(x, 0) = \varphi(x), u_t(x, 0) = \psi(x) & x \in \Omega \quad \text{初值 (必)} \\ u|_{\partial\Omega} = h(x, t) & t \geq 0 \quad \text{第一边值} \end{cases}$$

该方程最多有一个古典解。

pr: 设 (\*) 有两个解  $u_1, u_2$ .

$$\text{令 } u(x, t) = u_1(x, t) - u_2(x, t)$$

$$\text{则 } \begin{cases} \Delta_t^2 u - \Delta u = 0 \\ u(x, 0) = 0, u_t(x, 0) = 0 \\ u|_{\partial\Omega} = 0 \end{cases}$$

$$\text{由能量估计, 令 } E(t) = \frac{1}{2} \int_{\Omega} u_t^2 + |u| \, dx$$

$$\text{则 } E(t) = E(0) = 0$$

$$\Rightarrow u_t = 0, \nabla u = \bar{0} \quad \forall x \text{ in } \Omega, t \geq 0$$

$$\Rightarrow u = \text{const} \quad \text{in } \Omega$$

由于  $u$  边值为 0, 为使得  $u$  连续于边界,  $u \equiv 0$

Rmk. 对第二类边值, 能量估计时

$$\frac{d}{dt} \int_{\Omega} \frac{1}{2} (u_t)^2 + \frac{1}{2} |u| \, dx = \int_{\partial\Omega} u_t \frac{\partial u}{\partial n} \, ds$$

给出  $\frac{\partial u}{\partial n} = 0$  的条件可类比  $u_t$  处理

对第三类边值,  $\frac{\partial u}{\partial n} + \alpha u = 0 \ (\alpha > 0), x \in \partial\Omega$

$$\text{def. } E(t) = \frac{1}{2} \int_{\Omega} u_t^2 + |u| \, dx + \frac{1}{2} \int_{\partial\Omega} \alpha u^2 \, dx$$

$$\text{此时 } \frac{dE(t)}{dt} = 0$$

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$$\text{考虑 } \begin{cases} \partial_t^2 u - \Delta u = f(x, t) & x \in \Omega, t > 0 \\ u(x, 0) = \varphi(x), u_t(x, 0) = \psi(x) & x \in \Omega \quad \text{初值} \quad (\text{必}) \\ u|_{\partial\Omega} = 0 & t \geq 0 \quad \text{第一边值} \end{cases}$$

(必) 的解在下述条件下关于初值和右端项稳定:

$$\forall \varepsilon > 0, \exists \eta = \eta(\varepsilon, T), \text{ s.t.}$$

$$\text{若 } \|\varphi_1 - \varphi_2\|_{L^2(\Omega)} \leq \eta, \|\nabla \varphi_1 - \nabla \varphi_2\|_{L^2(\Omega)} \leq \eta, \|\psi_1 - \psi_2\|_{L^2(\Omega)} \leq \eta$$

$$\|f_1 - f_2\|_{L^2(0, T; \Omega)} \leq \eta$$

则以  $\varphi_1, \psi_1$  为初值,  $f_1$  为右端项的解  $u_1$

与以  $\varphi_2, \psi_2$  为初值,  $f_2$  为右端项的解  $u_2$

$$\text{其在 } 0 \leq t \leq T \text{ 上满足 } \|u_1 - u_2\|_{L^2(\Omega)} + \|\nabla u_1 - \nabla u_2\|_{L^2(\Omega)} \leq \varepsilon$$

$$\|\partial_t u_1 - \partial_t u_2\|_{L^2(\Omega)} \leq \varepsilon$$

$$\text{Rmk. } \|f\|_{L^2(\Omega)} = \left( \int_{\Omega} |f(x)|^2 dx \right)^{\frac{1}{2}}$$

$$\|f\|_{L^2(0, T; \Omega)} = \left( \int_0^T \int_{\Omega} |f(x, t)|^2 dx dt \right)^{\frac{1}{2}}$$

$$\text{pr: 令 } u(x, t) = u_1(x, t) - u_2(x, t)$$

$$f = f_1 - f_2, \varphi = \varphi_1 - \varphi_2, \psi = \psi_1 - \psi_2$$

$$\text{则 } \begin{cases} \partial_t^2 u - \Delta u = f_1 - f_2 = f \\ u(x, 0) = \varphi_1 - \varphi_2 = \varphi, u_t(x, 0) = \psi_1 - \psi_2 = \psi \\ u|_{\partial\Omega} = 0 \end{cases}$$

$$u_t (\partial_t^2 u - \Delta u) = \partial_t \left[ \frac{1}{2} (u_t)^2 + \frac{1}{2} |\nabla u|^2 \right] - \text{div} (u_t \nabla u) = u_t \cdot f$$

$$\text{在 } \Omega \text{ 上积分, } \partial_t \int_{\Omega} \frac{1}{2} (u_t)^2 + \frac{1}{2} |\nabla u|^2 dx = \int_{\Omega} u_t f dx \leq \int_{\Omega} \frac{1}{2} f^2 + \frac{1}{2} (u_t)^2 dx$$

$$\frac{d}{dt} E(u) \leq \frac{1}{2} \int_{\Omega} f^2 dx + \frac{1}{2} \int_{\Omega} (u_t)^2 dx \leq \int_{\Omega} \frac{1}{2} f^2 dx + E(t)$$

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$$\frac{d}{dt} (e^{-t} E(t)) \leq \frac{1}{2} e^{-t} \int_{\Omega} f^2 dx$$

由 Gronwall,  $e^{-t} E(t) - E(0) \leq \frac{1}{2} \int_0^t e^{-s} \int_{\Omega} f^2(x,s) dx ds$

$$\Rightarrow E(t) \leq e^t (E(0) + \frac{1}{2} \int_0^t e^{-s} \int_{\Omega} f^2(x,s) dx ds)$$

$$\leq e^t (E(0) + \frac{1}{2} \int_0^t \int_{\Omega} f^2(x,s) dx ds)$$

$$\leq e^T (E(0) + \frac{1}{2} \int_0^T \int_{\Omega} f^2(x,s) dx ds)$$

$$\leq C_{1T} (E(0) + \int_0^T \int_{\Omega} f^2(x,s) dx ds) \quad \forall 0 \leq t \leq T \quad C_{1T} = \text{const. 与 } T \text{ 有关}$$

$E(0)$  是  $\int_{\Omega} \frac{1}{2}(u_0)^2 + \frac{1}{2}|\nabla u_0|^2 dx$  的初值

$$\text{令 } y(t) = \int_{\Omega} |u|^2 dx$$

$$y'(t) = 2 \int_{\Omega} u_t u dx \leq \int_{\Omega} u^2 + u_t^2 dx \leq y(t) + 2E(t)$$

与  $T$  有关常数

$$\leq y(t) + 2C_{1T} (E(0) + \int_0^T \int_{\Omega} f^2(x,s) dx ds)$$

$$\frac{d}{dt} (e^{-t} y(t)) \leq 2C_{1T} (E(0) + \int_0^T \int_{\Omega} f^2(x,s) dx ds)$$

由 Gronwall,  $e^{-t} y(t) - y(0) \leq t \cdot 2C_{1T} (E(0) + \int_0^T \int_{\Omega} f^2(x,s) dx ds)$

$$\Rightarrow y(t) \leq e^t [y(0) + t \cdot 2C_{1T} (E(0) + \int_0^T \int_{\Omega} f^2(x,s) dx ds)]$$

$$\leq e^T [y(0) + T \cdot 2C_{1T} (E(0) + \int_0^T \int_{\Omega} f^2(x,s) dx ds)]$$

$$\leq C_{2T} (y(0) + E(0) + \int_0^T \int_{\Omega} f^2(x,s) dx ds)$$

$$\text{则 } \|u(t)\|_{L^2(\Omega)}^2 + \|u\|_{L^2(\Omega)}^2 + \|\nabla u\|_{L^2(\Omega)}^2$$

$$\leq C_T (\|\varphi\|_{L^2(\Omega)}^2 + \|\psi\|_{L^2(\Omega)}^2 + \|\nabla \varphi\|_{L^2(\Omega)}^2 + \int_0^T \int_{\Omega} f^2(x,s) dx ds)$$

↑  
与  $T$  有关的常数

$$\leq 4\eta^2 C_T \triangleq \frac{\varepsilon}{2} = \varepsilon$$

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$$\text{考虑 } \begin{cases} \partial_t^2 u - \Delta u = 0 \\ u(x, 0) = \varphi(x), u_t(x, 0) = \psi(x) \end{cases} \quad x \in \mathbb{R}^3$$

两边同乘  $u_t$ , 有  $\partial_t e(u) - \operatorname{div}(u_t \nabla u) = 0$



在锥体  $|x-x_0| \leq R-t$  上积分



$$\iint_{\Delta} \partial_t e(u) - \operatorname{div}(u_t \nabla u) dx dt = 0$$

$$\text{右} = \iint_{\Delta} (\partial_t \nabla_x) \cdot (e(u), -u_t \nabla u) dx dt$$

$$k: |x-x_0|^2 = |R-t|^2$$

$$= \int_{\partial \Delta} (e(u), -u_t \nabla u) \cdot \bar{n} ds$$

$$\varphi(x, t) = |x-x_0|^2 - |R-t|^2 = 0$$

$$= -\int_B e(u)(0) dx + \int_T e(u)(t) dx$$

$$\nabla \varphi = (2(R-t), 2(x-x_0))$$

↑  
表示时间取值

$$n = \frac{\pm \nabla \varphi}{\|\nabla \varphi\|} = \pm \frac{1}{\sqrt{2}} \left( \frac{R-t}{|R-t|}, \frac{x-x_0}{|x-x_0|} \right)$$

$$+ \int_k (e(u), -u_t \nabla u) \cdot \frac{1}{\sqrt{2}} \left( \frac{R-t}{|R-t|}, \frac{x-x_0}{|x-x_0|} \right)$$

$$\Rightarrow \int_B e(u)(0) dx = \int_T e(u)(t) dx + \frac{1}{\sqrt{2}} \int_k \left( \frac{1}{2}(u_t)^2 + \frac{1}{2}|\nabla u|^2 \right) \frac{R-t}{|R-t|} - u_t \nabla u \cdot \frac{x-x_0}{|x-x_0|} ds$$

$$= \int_T e(u)(t) dx + \frac{1}{\sqrt{2}} \int_k (u_t)^2 + |\nabla u|^2 - 2u_t \nabla u \cdot \frac{x-x_0}{|x-x_0|} ds$$

$$= \int_T e(u)(t) dx + \frac{1}{\sqrt{2}} \int_k \left| u_t - \frac{x-x_0}{|x-x_0|} \cdot \nabla u \right|^2 + |\nabla u|^2 - \left| \frac{x-x_0}{|x-x_0|} \cdot \nabla u \right|^2 ds$$

Flux  $[0, t] \geq 0$

$$\text{即 } \int_B e(u)(0) dx = \int_T e(u)(t) dx + \text{Flux } [0, t]$$

( $t=0$  处能量)

( $t=t_0$  处能量)

(能量溢出)

若  $(u, u_t)|_{r=0} = 0$ , 在  $B$  上能量为 0, 则在  $(u, u_t)$  在  $T$  上恒为 0

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## §4.2 混合问题

混合问题即初边值问题

$$\begin{cases} \Delta^2 u - \Delta u = f(x, t) \\ u(x, 0) = \varphi(x), u_t(x, 0) = \psi(x) \\ u|_{\partial\Omega} = g(x, t) / \frac{\partial u}{\partial n}|_{\partial\Omega} = g_1(x, t) / \frac{\partial u}{\partial n} + \alpha u|_{\partial\Omega} = g_2(x, t) \end{cases} \quad x \in \Omega, t > 0$$

### 4.2.1 常微分方程齐次边值问题

$$\begin{cases} x'' + \lambda x = 0 & x \in (0, l) \\ -\alpha_1 x'(0) + \beta_1 x(0) = 0 \\ \alpha_2 x'(l) + \beta_2 x(l) = 0 \end{cases} \quad (3.15)$$

$$\alpha_i \geq 0, \beta_i \geq 0, \alpha_i + \beta_i > 0, i = 1, 2$$

称为 Sturm-Liouville 特征值问题,  $\lambda$  称为特征值

$\lambda \in \mathbb{R}$  称为特征值, 相应于  $\lambda$  的非零解  $x(x)$  称为对应于这个特征值的特征函数

thm (1) 所有特征值为非负实数

$\beta_1 + \beta_2 > 0$  时, 所有特征值为正数

(2) 不同特征值对应特征函数正交.

$$\text{即 } \int_0^l X_{\lambda}(x) X_{\mu}(x) dx = 0$$

(3)  $\lambda_1, \dots, \lambda_n, \dots$  为特征值

$$0 \leq \lambda_1 < \lambda_2 < \dots < \lambda_n < \dots \quad \lim_{n \rightarrow \infty} \lambda_n = +\infty$$

(4)  $f(x) \in C^2(0, l)$  可按特征函数系展开为

$$\begin{aligned} f(x) &= \sum_{n=1}^{\infty} C_n X_n(x) \\ C_n &= \frac{\int_0^l f(x) X_n(x) dx}{\int_0^l X_n^2(x) dx} \end{aligned}$$

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$$p=1: X'' + \lambda X = 0 \Rightarrow X X'' + \lambda X^2 = 0$$

$$X X'' + \lambda X^2 = (X X')' - (X')^2 + \lambda X^2 = 0$$

$$\begin{aligned} \Rightarrow \lambda \int_0^l X^2 dx &= \int_0^l (X')^2 dx - \int_0^l (X X')' dx \\ &= \int_0^l (X')^2 dx - X X' \Big|_{x=0}^{x=l} \\ &= \int_0^l (X')^2 dx + X(0) X'(0) - X(l) X'(l) \end{aligned}$$

$$-\alpha_1 X'(0) + \beta_1 X(0) = 0 \Rightarrow -\alpha_1 X'(0)^2 + \beta_1 X(0) X'(0) = 0$$

$$-\alpha_1 X'(0) X(0) + \beta_1 X(0)^2 = 0$$

$$\Rightarrow X(0) X'(0) = \frac{\alpha_1}{\alpha_1 + \beta_1} X'(0)^2 + \frac{\beta_1}{\alpha_1 + \beta_1} X(0)^2$$

$$\text{类似地, } X(l) X'(l) = -\frac{\alpha_2 X'(l)^2 + \beta_2 X(l)^2}{\alpha_2 + \beta_2}$$

代入表达式有

$$\lambda \int_0^l X^2 dx = \int_0^l (X')^2 dx + \frac{\alpha_1}{\alpha_1 + \beta_1} X'(0)^2 + \frac{\beta_1}{\alpha_1 + \beta_1} X(0)^2 + \frac{\alpha_2}{\alpha_2 + \beta_2} X'(l)^2 + \frac{\beta_2}{\alpha_2 + \beta_2} X(l)^2$$

$$\geq 0 \Rightarrow \lambda \geq 0$$

$$\lambda = 0 \Leftrightarrow X' = 0, \text{ 且 } \frac{\beta_1}{\alpha_1 + \beta_1} X(0)^2 + \frac{\beta_2}{\alpha_2 + \beta_2} X(l)^2 = 0$$

故  $\beta_1 = \beta_2 = 0$  时,  $X(x) = \text{Const}$

若  $\beta_1, \beta_2$  中有一个不为 0,  $X(x) = \text{Const} = 0$ , 0 不为特征值

(2) 设  $X_\lambda, X_\mu$  为不同特征值  $\lambda, \mu$  的特征函数

$$\text{则 } X_\lambda'' + \lambda X_\lambda = 0$$

$$X_\mu'' + \mu X_\mu = 0$$

$$\lambda \int_0^l X_\lambda X_\mu dx = -\int_0^l X_\mu X_\lambda'' dx = -\int_0^l X_\mu d(X_\lambda') = \int_0^l X_\lambda' X_\mu' dx - X_\mu X_\lambda' \Big|_0^l$$

$$= X_\mu(0) X_\lambda'(0) - X_\mu(l) X_\lambda'(l) + \int_0^l X_\lambda' X_\mu' dx$$

$$\text{同理有结果, } \mu \int_0^l X_\lambda X_\mu dx = X_\lambda(0) X_\mu'(0) - X_\mu'(l) X_\lambda(l) + \int_0^l X_\lambda' X_\mu' dx$$

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相减可得

$$(\lambda - \mu) \int_0^1 X_\lambda X_\mu dx = (X_\lambda'(0) X_\mu(0) - X_\mu'(0) X_\lambda(0)) - (X_\mu'(1) X_\lambda(1) - X_\mu'(1) X_\lambda(1))$$

$$\text{即也表示 } \begin{cases} -\alpha_1 X_\lambda'(0) + \beta_1 X_\lambda(0) = 0 & (1) \\ \alpha_2 X_\lambda'(1) + \beta_2 X_\lambda(1) = 0 & (2) \end{cases}$$

$$\begin{cases} -\alpha_1 X_\mu'(0) + \beta_1 X_\mu(0) = 0 & (3) \\ \alpha_2 X_\mu'(1) + \beta_2 X_\mu(1) = 0 & (4) \end{cases}$$

(1)(2) 构成关于  $\alpha_1, \beta_1$  的线性方程, 有非零解, 则

$$\begin{vmatrix} X_\lambda'(0) & X_\lambda(0) \\ X_\mu'(0) & X_\mu(0) \end{vmatrix} = 0 \Rightarrow X_\lambda'(0) X_\mu(0) - X_\lambda(0) X_\mu'(0) = 0$$

$$\text{同理 } X_\mu'(1) X_\lambda(1) - X_\mu(1) X_\lambda'(1) = 0$$

$$\lambda \neq \mu \Rightarrow \int_0^1 X_\lambda X_\mu dx = 0$$

Rmk. (3)(4) 的证明在泛函分析中学到

相应的  $L^2$ -阻基是由于算子  $\frac{d^2}{dx^2}$  为对称紧算子

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## §4.2.2 分离变量法

$$\text{考虑 } \begin{cases} \partial_t^2 u - \partial_x^2 u = f(x, t) & 0 < x < l, t > 0 \\ u(x, 0) = \varphi(x), u_t(x, 0) = \psi(x) & 0 \leq x \leq l \\ u(0, t) = g_1(t), u(l, t) = g_2(t) & t > 0 \end{cases}$$

(一) 恒定弦的振动

$$1. f=0, g_1(t), g_2(t) \equiv 0$$

$$\text{则 } \begin{cases} \partial_t^2 u - \partial_x^2 u = 0 & 0 < x < l, t > 0 \\ u(x, 0) = \varphi(x), u_t(x, 0) = \psi(x) & 0 \leq x \leq l \\ u(0, t) = 0, u(l, t) = 0 & t > 0 \end{cases}$$

①  $u$  只与  $t$  有关, 则  $\partial_t^2 u = 0 \Rightarrow u = C_1 t + C_2$

$$u(0, t) = C_1 t + C_2 \text{ 不满足边界}$$

②  $u$  只与  $x$  有关, 则  $\partial_t^2 u = 0 \Rightarrow u = C_1 x + C_2$

$$u(x, 0) = C_1 x + C_2 = \varphi(x) \text{ 不容易满足初值}$$

③ 令  $u(x, t) = T(t) X(x)$

$$\text{则 } T''(t) X(x) - T(t) X''(x) = 0$$

$$T(t) \cdot X(x) \neq 0 \Rightarrow \frac{T''(t)}{T(t)} = \frac{X''(x)}{X(x)} \triangleq -\lambda$$

$$\Rightarrow \begin{cases} X''(x) + \lambda X(x) = 0 \\ T''(t) + \lambda T(t) = 0 \end{cases}$$

$$\begin{cases} u(0, t) = 0 \\ u(l, t) = 0 \end{cases} \Rightarrow \begin{cases} T(t) X(0) = 0 \\ T(t) X(l) = 0 \end{cases} \quad \forall t \geq 0$$

$$\Rightarrow X(0) = X(l) = 0$$

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考虑关于  $x$  的 Sturm-Liouville 边值问题

$$\begin{cases} X''(x) + \lambda X(x) = 0 \\ X(0) = 0 \\ X(l) = 0 \end{cases}$$

$$0 = \int_0^l X(x) (X''(x) + \lambda X(x)) dx = X(x)X'(x) \Big|_0^l - \int_0^l (X'(x))^2 dx + \lambda \int_0^l (X(x))^2 dx$$

$$\Rightarrow \lambda \int_0^l (X(x))^2 dx = \int_0^l (X'(x))^2 dx$$

$$\Rightarrow \lambda \geq 0$$

若  $\lambda = 0$ , 则  $X''(x) = 0 \Rightarrow X(x) = C_1 x + C_2$

$$X(0) = C_2 = 0, X(l) = C_1 l = 0 \Rightarrow C_1 = 0 \Rightarrow X(x) \equiv 0$$

若  $\lambda > 0$ ,  $X''(x) + \lambda X(x) = 0$

$$\Rightarrow X(x) = C_1 \cos \sqrt{\lambda} x + C_2 \sin \sqrt{\lambda} x$$

$$X(0) = C_1 = 0, X(l) = C_2 \sin \sqrt{\lambda} l = 0 \quad \sqrt{\lambda} l = n\pi \quad n \in \mathbb{Z}^+$$

$$\Rightarrow \lambda_n = \left(\frac{n\pi}{l}\right)^2 \quad n = 1, 2, \dots$$

与之对应的特征函数  $X_n(x) = \sin\left(\frac{n\pi}{l}x\right)$  (事实上为  $C_2 \sin\left(\frac{n\pi}{l}x\right)$ , 但系数可被 "Cn" "Dn" 吸收)

由于  $T_n''(t) + \lambda_n T_n(t) = 0$

$$T_n(t) = C_n \cos\left(\frac{n\pi}{l}t\right) + D_n \sin\left(\frac{n\pi}{l}t\right)$$

$$\text{令 } u(x, t) = \sum_{n=1}^{\infty} \left[ C_n \cos\left(\frac{n\pi}{l}t\right) + D_n \sin\left(\frac{n\pi}{l}t\right) \right] \sin\left(\frac{n\pi}{l}x\right)$$

再利用初值条件.

$$u(x, 0) = \sum_{n=1}^{\infty} C_n \sin\left(\frac{n\pi}{l}x\right) = \varphi(x)$$

$$u_t(x, 0) = \sum_{n=1}^{\infty} \frac{n\pi}{l} D_n \sin\left(\frac{n\pi}{l}x\right) = \psi(x)$$

由 Sturm-Liouville,  $\left\{ \sin\left(\frac{n\pi}{l}x\right) \right\}_{n=1}^{\infty}$  为  $L^2$  中一组正交基

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$$\varphi(x) = \sum_{n=1}^{\infty} \varphi_n \sin\left(\frac{n\pi}{l}x\right)$$

$$\varphi_n = \frac{\int_0^l \varphi(x) \sin\left(\frac{n\pi}{l}x\right) dx}{\int_0^l \sin^2\left(\frac{n\pi}{l}x\right) dx} = \frac{2}{l} \int_0^l \varphi(x) \sin\left(\frac{n\pi}{l}x\right) dx$$

$$\psi(x) = \sum_{n=1}^{\infty} \psi_n \sin\left(\frac{n\pi}{l}x\right)$$

$$\psi_n = \frac{\int_0^l \psi(x) \sin\left(\frac{n\pi}{l}x\right) dx}{\int_0^l \sin^2\left(\frac{n\pi}{l}x\right) dx} = \frac{2}{l} \int_0^l \psi(x) \sin\left(\frac{n\pi}{l}x\right) dx$$

$$\Rightarrow \left. \begin{aligned} C_n &= \varphi_n = \frac{2}{l} \int_0^l \varphi(x) \sin\left(\frac{n\pi}{l}x\right) dx \\ D_n &= \frac{1}{n\pi} \psi_n = \frac{2}{n\pi} \int_0^l \psi(x) \sin\left(\frac{n\pi}{l}x\right) dx \end{aligned} \right\} \varphi, \psi$$

故原方程解为

$$u(x, t) = \sum_{n=1}^{\infty} \left[ C_n \cos\left(\frac{n\pi}{l}t\right) + D_n \sin\left(\frac{n\pi}{l}t\right) \right] \sin\left(\frac{n\pi}{l}x\right)$$

其中  $C_n, D_n$  由(\*) 给出

thm 相容性条件

若  $\varphi \in C^1([0, l]), \psi \in C^1([0, l]), \varphi(x), \psi(x)$  在  $(0, l) \times (0, +\infty) \triangleq \bar{Q}$

角点满足相容性条件  $\varphi(0) = \varphi(l) = \varphi'(0) = \varphi'(l) = \psi(0) = \psi(l) = 0$

则  $u(x, t) \in C^2(\bar{Q})$  为古典解

Rmk. 若  $u(x, t) = \sum_{n=1}^{\infty} T_n(t) X_n(x)$

$T_n, X_n$  均足够好, 使得微分与求和可换序

$$\begin{aligned} \text{则 } \partial_t^2 u - \partial_x^2 u &= \sum_{n=1}^{\infty} T_n''(t) X_n(x) - T_n(t) X_n''(x) \\ &= \sum_{n=1}^{\infty} \left( T_n''(t) + \lambda_n T_n(t) \right) X_n(x) = 0 \end{aligned}$$

2.  $f \neq 0, g_1(t), g_2(t) \equiv 0$

$$\text{令 } f(x, t) = \sum_{n=1}^{\infty} f_n(t) \sin\left(\frac{n\pi}{l}x\right)$$

$$\varphi(x) = \sum_{n=1}^{\infty} \varphi_n \sin\left(\frac{n\pi}{l}x\right), \psi(x) = \sum_{n=1}^{\infty} \psi_n \sin\left(\frac{n\pi}{l}x\right)$$

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$$\text{令 } u(x, t) = \sum_{n=1}^{\infty} T_n(t) \sin\left(\frac{n\pi}{l}x\right)$$

$$\text{代入 } \partial_t^2 u - \partial_x^2 u = f(x, t)$$

$$\text{有 } \sum_{n=1}^{\infty} (T_n''(t) + \lambda_n T_n(t)) \sin\left(\frac{n\pi}{l}x\right) = \sum_{n=1}^{\infty} f_n(t) \sin\left(\frac{n\pi}{l}x\right)$$

$$\text{则 } T_n \text{ 满足方程 } T_n''(t) + \lambda_n T_n(t) = f_n(t)$$

$$u(x, 0) = \sum_{n=1}^{\infty} T_n(0) \sin\left(\frac{n\pi}{l}x\right) = \sum_{n=1}^{\infty} \varphi_n \sin\left(\frac{n\pi}{l}x\right) \Rightarrow T_n(0) = \varphi_n$$

$$u_t(x, 0) = \sum_{n=1}^{\infty} T_n'(0) \sin\left(\frac{n\pi}{l}x\right) = \sum_{n=1}^{\infty} \psi_n \sin\left(\frac{n\pi}{l}x\right) \Rightarrow T_n'(0) = \psi_n$$

$$\Rightarrow T_n(t) = \varphi_n \cos\left(\frac{n\pi}{l}t\right) + \frac{1}{n\pi} \psi_n \sin\left(\frac{n\pi}{l}t\right) + \frac{1}{n\pi} \int_0^t f_n(\tau) \sin\left(\frac{n\pi}{l}(t-\tau)\right) d\tau \quad (*)$$

原问题的特解为

$$u(x, t) = \sum_{n=1}^{\infty} T_n(t) \sin\left(\frac{n\pi}{l}x\right) \quad T_n \text{ 由 } (*) \text{ 给出}$$

3.  $f \neq 0, g_1, g_2 \neq 0$

$$\text{令 } v(x, t) = u(x, t) - \frac{(1-x)g_1(t) + xg_2(t)}{l}$$

$$\left. \begin{aligned} \text{则 } v(0, t) &= u(0, t) - g_1(t) = 0 \\ v(l, t) &= u(l, t) - g_2(t) = 0 \end{aligned} \right\} \text{边界条件}$$

$$\left\{ \begin{aligned} \partial_t^2 v - \partial_x^2 v &= f(x, t) - \frac{(1-x)g_1''(t) + xg_2''(t)}{l} \\ v(x, 0) &= \varphi(x) - \frac{(1-x)g_1(0) + xg_2(0)}{l} \\ v_t(x, 0) &= \psi(x) - \frac{(1-x)g_1'(0) + xg_2'(0)}{l} \end{aligned} \right.$$

从而转化为零边界问题

Rank. 本段为 S-L 边界问题的特征系展开, 与右端类型无关.

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ex. (热传导方程)

$$\begin{cases} u_t = u_{xx} & 0 < x < l \\ u(x, 0) = \varphi(x) \\ u(0, t) = 0, \quad u_x(l, t) + hu(l, t) = 0 \quad h > 0 \end{cases}$$

设  $u(x, t) = T(t)X(x)$

则  $T'(t)X(x) = T(t)X''(x)$

$$\Rightarrow \frac{T'(t)}{T(t)} = \frac{X''(x)}{X(x)} = -\lambda$$

$$u(0, t) = 0 \Rightarrow T(t)X(0) = 0$$

$$u_x(l, t) + hu(l, t) = 0 \Rightarrow T(t)X'(l) + hT(t)X(l) = 0$$

$$\text{对 } \forall t \text{ 成立, 只需 } X'(l) + hX(l) = 0$$

故  $X(x)$  满足边值问题

$$\begin{cases} X''(x) + \lambda X(x) = 0 \\ X(0) = 0 \\ X'(l) + hX(l) = 0 \end{cases}$$

$$\textcircled{1} \lambda < 0 \text{ 时, } X(x) = C_1 e^{\sqrt{-\lambda}x} + C_2 e^{-\sqrt{-\lambda}x}$$

$$X(0) = 0 \Rightarrow C_1 + C_2 = 0$$

$$C_1 \sqrt{-\lambda} e^{\sqrt{-\lambda}l} - C_2 \sqrt{-\lambda} e^{-\sqrt{-\lambda}l} + h(C_1 e^{\sqrt{-\lambda}l} + C_2 e^{-\sqrt{-\lambda}l}) = 0$$

$$C_1 [\sqrt{-\lambda} e^{\sqrt{-\lambda}l} + \sqrt{-\lambda} e^{-\sqrt{-\lambda}l}] + h(e^{\sqrt{-\lambda}l} - e^{-\sqrt{-\lambda}l}) = 0$$

$$\Leftrightarrow C_1 = 0 \text{ 或 } \begin{cases} \sqrt{-\lambda} + h = 0 \\ \sqrt{-\lambda} - h = 0 \end{cases} \Rightarrow h = 0$$

$$\text{故 } C_1 = 0, C_2 = 0$$

Remark. 利用本方法同样可说明  $\lambda \geq 0$ , 同乘  $x$  为  $S-L$  问题的手段

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②  $\lambda = 0$  时,  $X(x) = C_1 x + C_2$

$$X(0) = C_2 = 0$$

$$X'(l) + hX(l) = C_1 + hC_1 l = 0 \Rightarrow C_1 = 0 \Rightarrow X(x) \equiv 0$$

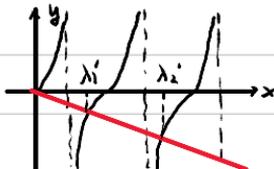
若  $\lambda > 0$ , 则  $X(x) = C_1 \cos(\sqrt{\lambda}x) + C_2 \sin(\sqrt{\lambda}x)$

$$X(0) = C_1 = 0$$

$$X'(l) + hX(l) = C_2 \sqrt{\lambda} (\cos(\sqrt{\lambda}l) + h \sin(\sqrt{\lambda}l)) = 0$$

$$C_2 \neq 0 \Rightarrow \tan(\sqrt{\lambda}l) = \frac{-\sqrt{\lambda}}{h}$$

考虑方程  $\tan x = \frac{-x}{hl}$  的解



$$\exists 0 < \lambda_1 < \dots < \lambda_n < \dots, \text{ 满足 } \tan(\sqrt{\lambda}l) = \frac{-\sqrt{\lambda}}{h}$$

令  $X_n(x) = \sin(\sqrt{\lambda_n}x)$  为  $\lambda_n$  对应的特征函数

$$T_n(t) \text{ 满足方程 } T_n' + \lambda_n T_n = 0 \Rightarrow T_n(t) = A_n e^{-\lambda_n t}$$

$$\text{则 } u(x, t) = \sum_{n=1}^{\infty} A_n e^{-\lambda_n t} \sin(\sqrt{\lambda_n}x)$$

$$\text{即 } u(x, 0) = \sum_{n=1}^{\infty} A_n \sin(\sqrt{\lambda_n}x) = \varphi(x) = \sum_{n=1}^{\infty} \varphi_n \sin(\sqrt{\lambda_n}x)$$

$$\Rightarrow A_n = \varphi_n = \frac{\int_0^l \varphi(x) \sin(\sqrt{\lambda_n}x) dx}{\int_0^l \sin^2(\sqrt{\lambda_n}x) dx}$$

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ex. (拉普拉斯方程)

$$\Omega = \{(x, y) \mid x^2 + y^2 < 1\}$$

考虑  $\Omega$  上拉普拉斯方程:

$$\begin{cases} \Delta u = 0 & \text{in } \Omega \\ u = \varphi & \text{in } \partial\Omega \end{cases}$$

$$\text{令 } \begin{cases} x = r \cos \theta \\ y = r \sin \theta \end{cases}$$

$$\Rightarrow \begin{cases} \Delta^2 u + \frac{1}{r} \partial_r u + \frac{1}{r^2} \partial_\theta^2 u = 0 & \text{in } \Omega \\ u|_{r=1} = \varphi(\cos \theta, \sin \theta) \triangleq \tilde{\varphi}(\theta) \end{cases}$$

$$\text{令 } u(r, \theta) = R(r) \Theta(\theta)$$

$$\text{则 } R''(r) \Theta(\theta) + \frac{1}{r} R'(r) \Theta(\theta) + \frac{1}{r^2} R(r) \Theta''(\theta) = 0$$

$$\Rightarrow -r^2 \frac{R''(r) + \frac{1}{r} R'(r)}{R(r)} = \frac{\Theta''(\theta)}{\Theta(\theta)} \triangleq -\lambda$$

分离  $\Theta(\theta)$  的方程

$$\begin{cases} \Theta''(\theta) + \lambda \Theta(\theta) = 0 \\ \Theta(\theta) = \Theta(\theta + 2\pi) \end{cases}$$

若  $\lambda < 0$ ,  $\Theta(\theta) = C_1 e^{-\sqrt{\lambda}\theta} + C_2 e^{\sqrt{\lambda}\theta}$ , 不以  $2\pi$  为周期

若  $\lambda = 0$ ,  $\Theta(\theta) = C_1 \theta + C_2$ , 不以  $2\pi$  为周期, 除非  $C_1 = 0$ , 即  $\Theta(\theta)$  为常数

若  $\lambda > 0$ ,  $\Theta(\theta) = C_1 \cos(\sqrt{\lambda}\theta) + C_2 \sin(\sqrt{\lambda}\theta)$

以  $2\pi$  为周期  $\Leftrightarrow \sqrt{\lambda} \in \mathbb{Z}^+$

则  $\Theta_n(\theta) = C_n \cos(n\theta) + D_n \sin(n\theta)$  为  $\lambda_n = n^2$  对应特征函数,  $n = 1, 2, \dots$

可构成空间-阻基由于  $\frac{d^2}{dt^2}$  为对称紧算子

(补充  $\Theta_0(\theta) = C_0$ )

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考虑  $R_n(r)$  满足的方程

$$r^2 R_n''(r) + r R_n'(r) - n^2 R_n = 0$$

为 Euler 方程.

$$\text{令 } r = e^t, \frac{dR_n}{dr} = R_n'(r)r, \frac{d^2 R_n}{dr^2} = R_n''(r)r^2 + R_n'(r)r = R_n''(r)r^2 + \frac{dR_n}{dt}$$

$$\text{故 } \frac{d^2 R_n}{dt^2} - n^2 R_n = 0$$

$$\Rightarrow R_n(t) = \begin{cases} C_1 e^{nt} + C_2 e^{-nt} = C_1 r^n + C_2 r^{-n} & n \neq 0 \\ C_1 t + C_2 = C_1 2n r + C_2 & n = 0 \end{cases}$$

$$\text{为使 } r=0 \text{ 处连续可做, 应取 } R_n(r) = \begin{cases} C_1 r^n & n \neq 0 \\ C_2 & n = 0 \end{cases}$$

$$\text{取 } C_1 = C_2 = 1.$$

$$\text{设 } u(r, \theta) = C_0 + \sum_{n=1}^{\infty} r^n (C_n \cos(n\theta) + D_n \sin(n\theta))$$

$$u|_{r=1} = C_0 + \sum_{n=1}^{\infty} C_n \cos(n\theta) + D_n \sin(n\theta) = \tilde{\varphi}(\theta)$$

$$C_n \int_0^{2\pi} \cos^2(n\theta) d\theta = \int_0^{2\pi} \tilde{\varphi}(\theta) \cos(n\theta) d\theta \Rightarrow C_n = \frac{1}{2} \int_0^{2\pi} \tilde{\varphi}(\theta) \cos(n\theta) d\theta$$

$$D_n \int_0^{2\pi} \sin^2(n\theta) d\theta = \int_0^{2\pi} \tilde{\varphi}(\theta) \sin(n\theta) d\theta \Rightarrow D_n = \frac{1}{2} \int_0^{2\pi} \tilde{\varphi}(\theta) \sin(n\theta) d\theta$$

$$C_0 \int_0^{2\pi} d\theta = \int_0^{2\pi} \tilde{\varphi}(\theta) d\theta \Rightarrow C_0 = \frac{1}{2\pi} \int_0^{2\pi} \tilde{\varphi}(\theta) d\theta$$

Rmk. 分离变量法对区域, 算子较为敏感